

TOW2025 - Seminar

FS Station Code

Alexander Neidhardt (TUM Wettzell)

Experience level: Beginners, Advanced.

<u>Description</u>: This course describes how to write station specific code with C. We discuss how other programs can easily interact with the FS shared memory and how to manage them.

FGS FESG * Endesant für Entegraphie und Geoetlisie

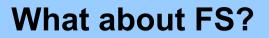
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FS Station Code

What about FS?

What does a station has to offer to the FS? How to control your antenna from FS? How to control your equipment from FS? How to fill data sets of the FS? How to add functionality to the FS? How to extend number of parallel devices? How to combine functionalities to the FS?





For general FS basics see:

TOW2023 - Maintenance Workshops

FS Operations

Alexander Neidhardt (TUM Wettzell)

Experience level: Beginners.

<u>Description</u>: This course describes the general structure of the NASA Field System, including important control files, program locations, handling, and so on. We will take a look into installation and setup. Main part is the use of the FS and the adaption of the PC for the Field System.

> Thanks for input from Simon Seidl (TUM Wettzell), Katherine Pazamickas (PERATON), and Ed Himwich (NVI)

> > Code: FSo1, FSo2



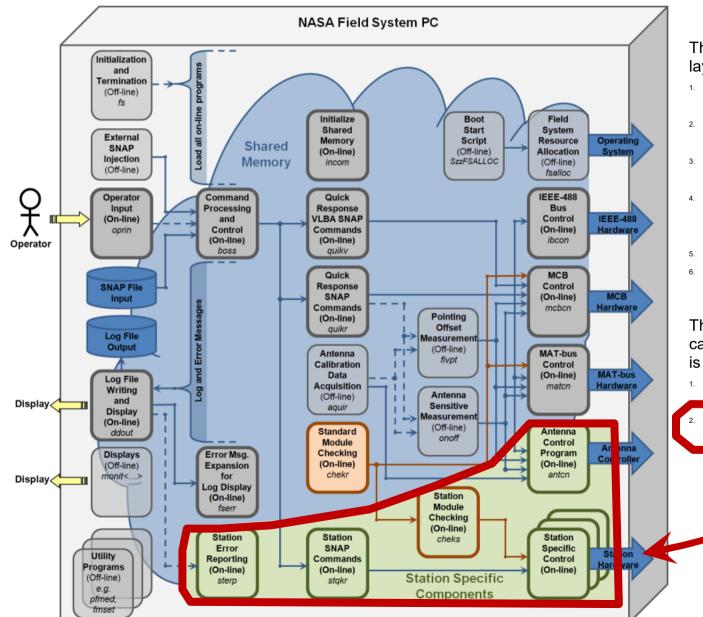
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FS Station Code

What about FS? What does a station has to offer to the FS?

How to control your antenna from FS? How to control your equipment from FS? How to fill data sets of the FS? How to add functionality to the FS? How to extend number of parallel devices? How to combine functionalities to the FS?





The NASA Field System can be split into six main layers:

- Programs for hardware control (hardware driving)
- Programs for (module) checking (monitoring)
- Programs for the SNAP command interpretation
- Programs for Command Processing and Control (coordination: «boss» or, e.g., the Antenna Calibration Data Acquisition «aquir»)
- 5. Programs for error reporting
- 6. Programs for user interfacing

The NASA Field System can be split into two categories, according to where the code is developed:

the general Field System programs from NASA/NVL (Himwich, Horsley, et. al.

station code, individually programmed by station staff



Station-specific programs

Antenna Control ("antcn")

Activated in dev.ctl

Station specific commands ("stqkr")

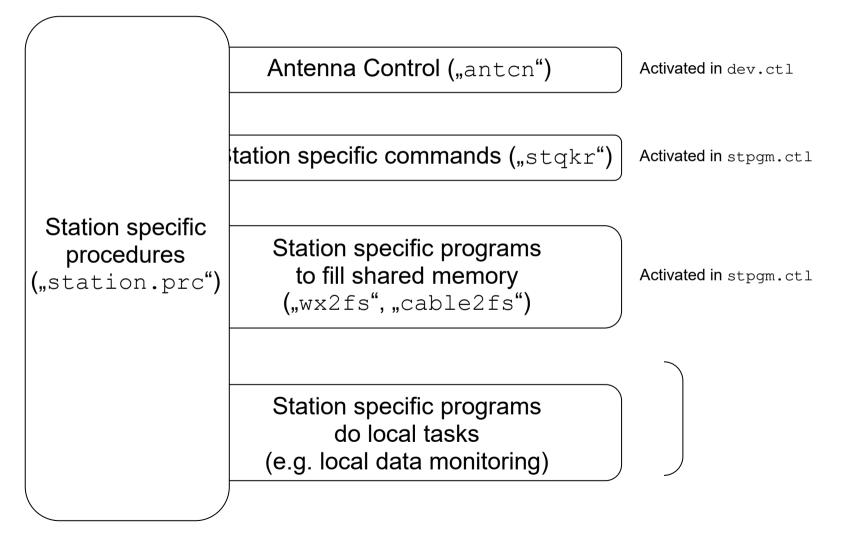
Activated in stpgm.ctl

Station specific programs to fill shared memory ("wx2fs", "cable2fs")

Activated in stpgm.ctl

Station specific programs do local tasks (e.g. local data monitoring)

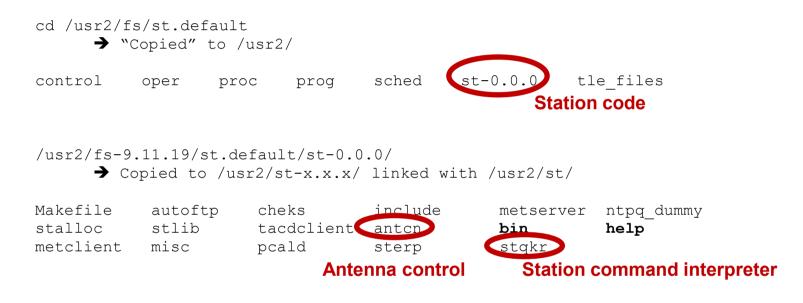






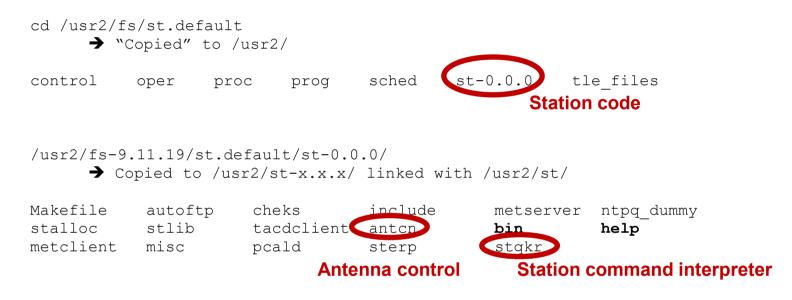








Station-specific programs



Station code can be very individual. Default programs are principally suggestions.

At least, you need:

- Antenna control program
 - (usually "antcn", but can have any name, must just fit to entries in /usr2/control/stpgm.ctl)
- Station QKR

(usually "stqkr", but can have any name, must just fit to entries in /usr2/control/stpgm.ctl)

- Meteo program
- Dotmon, cable (counter-reading) programs

Useful is:

- A directory with help pages
- A directory for binaries
- Maybe a directory for local control (configuration) files

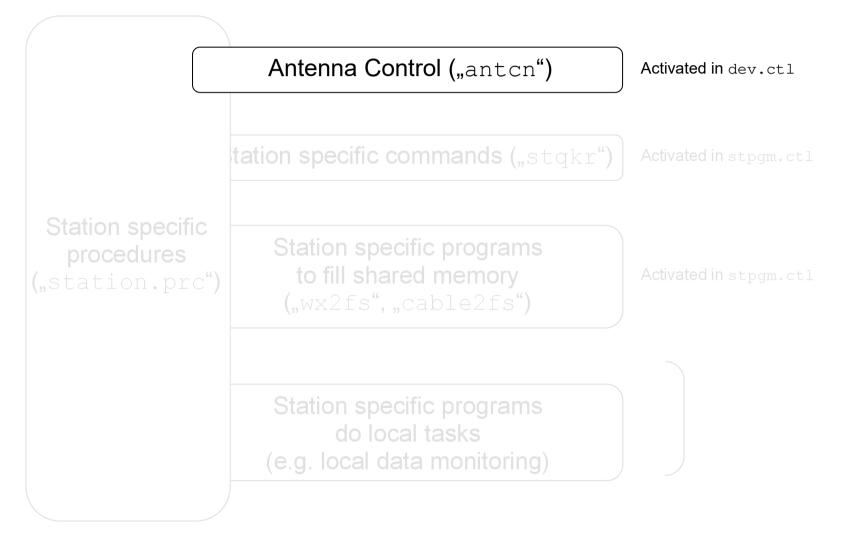


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FS Station Code

What about FS? What does a station has to offer to the FS? **How to control your antenna from FS?** How to control your equipment from FS? How to fill data sets of the FS? How to add functionality to the FS? How to extend number of parallel devices? How to combine functionalities to the FS?







Station QKR ("stqkr")

Sample "/usr2/control/stcmd.ctl":

* /usr2/cont					
******* F	ield System LU control file				
/dev/null	GPIB board device name, gpib0, or	serial	port	/dev/ttyS*	for GPIB-232CT
/dev/null	Mark III MAT device name				
9600	Mark III MAT baud rate				
/dev/null	Mark III Data Buffer device name				
9600	Mark III Data Buffer baud rate				
antcn	Antenna interface				
/dev/null	Barcode reader device name	T			
/dev/null	VLBA MCB device name	5			
57600	VLBA MCB baud rate				
/dev/null	ATNF Dataset device name				
38400	ATNF Dataset baud rate				

Activate "antcn" program



Antenna Control ("antcn")

	/* antcn.c	
	* * This is the stub version of antcn (ANTenna CoNtrol program). * This version sends a log message whenever it is called. */	
	<pre>/* Defined variables */ #define MINMODE 0 /* min,max modes for our operation */ #define MAXMODE 10 /* Include files */</pre>	
Include	<pre>#include <stdio.h> #include <string.h></string.h></stdio.h></pre>	Better in your program:
section	<pre>#include "//fs/include/params.h" /* FS parameters */ #include "//fs/include/fs_types.h" /* FS header files */</pre>	<i>-I with path in compiler call and just file names</i>
	<pre>*/ #include "//fs/include/fscom.h" /* FS shared mem. structure */ #include "//fs/include/shm_addr.h" /* FS shared mem. pointer */</pre>	here, e.g. #include <params.h></params.h>
Shared memory	struct fscom *fs; = NULL;	
Corresponding Functions to include section	<pre>/* Subroutines called */ void setup_ids(); void putpname(); void skd_run(), cls_clr(); int nsem_test(); void logit();</pre> Functions have arguments = => or directly use .h/.c file mathematically and the set of the	



Antenna Control ("antcn")

```
/* antcn main program starts here */
                            main()
                            ł
                              int ierr, nrec, nrecr;
                              int dum = 0;
                              int r1, r2;
                              int imode, i, nchar;
                              long ip[5], class, clasr;
                              char buf[80], buf2[100];
                            /* Set up IDs for shared memory, then assign the pointer to
                               "fs", for readability.
                            */
Init shared memory
                              setup ids();
                              fs = shm addr;
(just once!!!)
                            /* Put our program name where logit can find it. */
Define program name
                              putpname("antcn");
in FS environment
                            /* Return to this point to wait until we are called again */
```

>>>



Antenna Control ("antcn")

C	ontinue: skd_wait("antcn	Wait for ne ",ip,(unsigned)0); and receive	w command e command ID		
	<pre>imode = ip[0]; class = ip[1]; nrec = ip[2];</pre>	Split command ID: - Mode (com. number) - Class (for com. receive)	/* Handle each mod	le in a separate section */	
/		- Number of msg. parts	<pre>switch (imode) {</pre>		Command
		• •	case 0:	/* initialize */	switch and
	<pre>nrecr = 0; clasr = 0;</pre>	Init return values	 case 1:	/* source= command */	Call of antenna interface
			case 2:	/* offsets */	
	<pre>if (imode < MIN ierr = -1; goto End;</pre>	MODE imode > MAXMODE) {	case 3:	$/\star$ onsource command with error message $\star/$	
	5	error in command ID	case 4:	/* direct antenna= command */	
	Chicon		case 5:	<pre>/* onsource command with no error logging</pre>	*/
		>>>	case 6:	/* reserved */	
			case 7:	<pre>/* onsource command with additional info</pre>	*/
			case 8:	/* Station dependent detectors access */	
			case 9:	<pre>/* Satellite tracking mode */</pre>	
	Co	ommand	case 10:	<pre>/* normally triggered on FS termination if evironment variable FS_ANTCN_TERMINATION has been defined */</pre>	
		ocessing op	 default: 	-	nd:
_			} /* end of switc	- 01855	<pre>ip[0] = clasr; ip[1] = nrecr;</pre>
	etter: hile (true)		>>>	- Number of msg. parts - Error number	<pre>ip[2] = ierr; memcpy(ip+3,"AN",2); ip[4] = 0;</pre>
				- Application letter code	
					Page

Antenna Control ("antcn")

```
Continue:
  skd wait("antcn", ip, (unsigned) 0);
  imode = ip[0];
  class = ip[1];
                                                 /* Hand
  nrec = ip[2];
                                                   switd
                                                     cas
  nrecr = 0;
  clasr = 0;
  if (imode < MINMODE || imode > MAXMODE) {
    ierr = -1;
    goto End;
                       >>>
              Command
              Processing
                                                   default:
              Loop
```

On-source must be very conservative and not say the antenna is onsource when it isn't. This especially important when a new source or offset has been requested. We don't want the status for the previous source/offset, we want the latest commands taken into account (better say off-source sometimes when on-source than every say on when off).

```
case 1:
                 /* source= command
   . . .
                 /* offsets
                                     */
 case 2:
   . . .
                 /* onsource command with error message
 case 3:
                 /* direct antenna= command */
 case 4:
   . . .
                 /* onsource command with no error logging
 case 5:
   . . .
                 /* reserved */
 case 6:
   . . .
                 /* onsource command with additional info
 case 7:
   . . .
 case 8:
                 /* Station dependent detectors access */
   . . .
                 /* Satellite tracking mode */
 case 9:
 case 10:
                /* normally triggered on FS termination if
                   evironment variable FS ANTCN TERMINATION
                   has been defined */
   . . .
                                                            End:
/* end of switch */
                                                              ip[0] = clasr;
                                                              ip[1] = nrecr;
                                                              ip[2] = ierr;
       >>>
                                                              memcpy(ip+3, "AN", 2);
                                                              ip[4] = 0;
                                                              goto Continue;
```



Antenna Control ("antcn")

Sample:

```
/* initialize */
case 0:
   strncpy(acAnswerText, "Initializing Vertex ACU antenna interface", 79);
   logit(acAnswerText, 0, NULL);
   iFSErrorNumber = 0;
   if (iInitError)
   {
        strncpy(acAnswerText, "[ERROR] FS shared memory: init pointer is NULL", 79);
       logit(acAnswerText, 0, NULL);
                                                                                         Write message to log
       logit("", -5, "AN");
       exit(1);
   fs \rightarrow ionsor = 0;
   if (usCOpenInterface ("127.0.0.1", 0,
                         &ACUDescriptor) == CACUNOK)
   {
        strncpy(acAnswerText, "[ERROR] ACU: can't open interface", 79);
       logit(acAnswerText, 0, NULL);
                                               Write message to log defined in "/usr2/fs/control/fserr.ctl"
       logit("", -5, "AN");
       ACUDescriptor = NULL;
                                                                              .....
   if (usCStopAllAxis (&ACUDescriptor) == CACUNOK)
                                                                              AN
                                                                                      -5
    {
       logit("", -5, "AN");
                                                                              Error returned from antenna
        strncpy(acAnswerText, "[ERROR] ACU: can't stop movement", 79);
       logit(acAnswerText, 0, NULL);
                                                                             or in "/usr2/control/sterr.ctl"
   }
   usFSTrackingMode = FSTRACKINGMODE IDLE;
   if (usCMeteoOpenInterface ("127.0.0.1", 0,
                              &MeteoDescriptor) == CMETEO NOK)
   {
       strncpy(acAnswerText, "[ERROR] Meteo: can't open interface", 79);
       logit(acAnswerText, 0, NULL);
       logit("", -5, "AN");
       MeteoDescriptor = NULL;
       usUseMeteo = 0;
   }
   break;
```



Antenna Control ("antcn")

Sample:

```
case 1:
                /* source= command */
    /* Convert RADEC string */
    /* Get parameters for refraction correction */
    . . .
    if (usCMoveToRaDecPosition (&ACUDescriptor,
                                 (short)SFSTime.iYear,
                                 (short)SFSTime.iDoY,
                                 (short) SFSTime.iHour,
                                 (short) SFSTime. iMinute,
                                 (short)SFSTime.iSecond,
                                 0.0,
                                 dRightAscensionHour,
                                 dDeclinationDegree,
                                 SSourceStatus.acSourceStatus,
                                 usWrapIdentifier,
                                 usEpochIdentifier) == CACUNOK)
    {
        logit("", -5, "AN");
        strncpy(acAnswerText, "[ERROR] ACU: can't command position", 79);
        logit(acAnswerText, 0, NULL);
        goto Continue;
    }
    . . .
    break;
```

SNAP: source=1909+161,191158.26,161146.9,2000.0,cw source RA DEC YEAR Cable wrap Catalog

Please also read cable-wrap memo to get cable-wrap right: https://ivscc.gsfc.nasa.gov/meetings/tow2013/Himwich.Sem2.pdf



Antenna Control ("antcn")

Sample:

```
case 4:
                         /* direct antenna= command */
               if (class == 0)
                 goto End;
               for (i=0; i<nrec; i++) {</pre>
                 strcpy(buf2, "Received message for antenna: ");
                 nchar = cls_rcv(class, buf, sizeof(buf), &r1, &r2, dum, dum); Receive command
                 buf[nchar] = '\0'; /* make into a string */
                 strcat(buf2,buf);
                 logit(buf2,0,NULL);
                  . . .
                 for (iCommandCharIndex = 0; iCommandCharIndex < strlen(buf); ++iCommandCharIndex)</pre>
                                                                                                  Prepare command
                  {
                     acCommand[iCommandCharIndex] = (char)toupper((int)buf[iCommandCharIndex]);
                  }
SNAP:
                                */
                  /* antenna=halt or antenna=stop
antenna=halt
                  if (strlen(acCommand) == 4 &&
                     (!strncmp ("HALT", acCommand, 4) || !strncmp ("STOP", acCommand, 4)) &&
                     nrec == 1)
                 {
                     usFSTrackingMode = FSTRACKINGMODE IDLE;
                                                                                      Process command
                     strncpy(acAnswerText, "ACU: stop all axis", 79);
                     logit(acAnswerText, 0, NULL);
                     if (usCStopAllAxis (&ACUDescriptor) == CACUNOK)
                     {
                         logit("", -105, "AN");
                     }
                     else
                     {
                         strcpy(buf, "ACK");
                         cls snd(&clasr,buf,3,0,0);
                                                      Reply command
                         nrecr += 1;
                     }
                  /* OR: cls clr(class); */
               break;
```

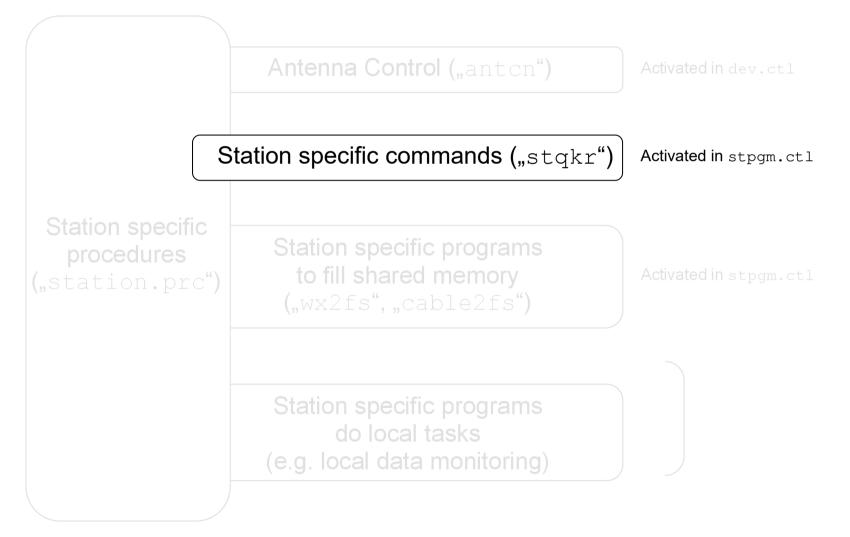
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FS Station Code

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How to control your equipment from FS?

```
Classic C-Code
                                               Station QKR ("stqkr"): stqkr.c
/* stgkr - C version of station command controller */
                                                                                                               Wait for incoming
                                                                     skd wait("stqkr", ip, (unsigned) 0);
#include <stdio.h>
                                                                     if(ip[0]==0) {
                                                                                                               orders
#include <string.h>
                                                                       ierr=-1:
#include <sys/types.h>
                                                                       goto error;
#include "../../fs/include/params.h"
#include "../../fs/include/fs types.h"
                                                                     nchars=cls rcv(ip[0],buf,MAX BUF,&idum,&idum,0,0);
                                                                     if(nchars==MAX_BUF && buf[nchars-1] != '\0' Receive command
#include "../../fs/include/fscom.h"
#include "../../fs/include/shm addr.h"
            /* shared memory pointer */
                                                                       ierr=-2;
                                                                                                               and arguments
                                                                       goto error;
#include "../include/stparams.h"
#include "../include/stcom.h"
                                                                     /* null terminate to be sure */
                                                                     if (nchars < MAX BUF && buf[nchars-1] != '\0')
                                                                       buf[nchars] = \sqrt{0};
struct stcom *st;
                                                                                                               Parse (interprete)
struct fscom *fs;
                                                                     if(0 != (ierr = cmd_parse(buf, &command))) { command and
                                                                       ierr=-3;
#define MAX BUF
                 257
                                                                                                               arguments
                                                                       goto error;
                                                           Loop
main()
                                                                                                                Performe action
   long ip[5];
                                                                     isub = ip[1]/100;
    int isub,itask,idum,ierr,nchars,i;
                                                                                                                according to
    char buf[MAX BUF];
                                                                     itask = ip[1] - 100*isub;
   struct cmd ds command;
                                                                                                                command
    int cls rcv(), cmd parse();
                                                                     switch (isub) {
                                                                                                                => Call function
   void skd wait();
                                                                        case 1:
                                                               /*
                                                                           call routine here to handle a task */
/* Set up IDs for shared memory, then assign the pointer to
                                                                           break;
 * "fs", for readability.
                                                                        case 2:
 */
                                                               /*
                                                                           call routine here to handle next task */
                                                                           break:
  setup ids();
                                                                        default:
                   Initialize
  fs = shm addr;
                                                                           ierr=-4;
  setup st();
                                                                           goto error;
                                                                                                                Prepare return
                                                                     goto loop;
                                                                                                                Values
                                                               error:
                                                                                                                => ACK
                                                                     for (i=0;i<5;i++) ip[i]=0;</pre>
      ➔ Principle similar to "antcn"
                                                                     ip[2]=ierr;
                                                                     memcpy(ip+3,"st",2);
                                                                     goto loop;
                                                                                                                               Page23
```



How to control your equipment from FS?

C/C++-Code

Station QKR ("stqkr"): stqkr.cpp

```
#include <stdio.h>
#include <stdlib.h>
#include "fsshm.h"
#include "simple structured conf.hpp"
#include "meteo.hpp"
#include "rxmon.hpp"
#include "testequip.hpp"
int main (int iArgc, char * pcArgv[])
{
    BOSSCOM BOSSCOMIdentifier = NULL; /// BOSSCOMIdentifier = Identification of current communication (it is a pointer to the data set
                                       /// "ip" of the field system)
    char acProgramName[6] = "stgkr";
                                       /// pcProgramName = name of the program, which waits for a message
    char acReceivedMessage[4096];
                                       /// acReceivedMessage = complete message sent from boss
    CSimpleStructuredConf CConfiguration; /// CConfiguration = the whole configuration parameters of the stgkr program
    unsigned long ulCurrentLineNumber; /// ulCurrentLineNumber = line number of the configuration file, where an error occured
    std::string strCurrentTag;
                                       /// strCurrentTag = tag in the configuration file, where the error occured
    printf ("stgkr: Startup ... \n");
    /// Open communication to NASA FS boss
    if (usOpenBossCommunication (&BOSSCOMIdentifier))
                                                                                  Initialize
    {
        printf ("[ERROR] stgkr: Cannot open connection to NASA FS boss\n");
        return 1;
    /// Check program parameters
    if (iArgc != 2)
    {
        (void) usPrintError2Log (&BOSSCOMIdentifier, acProgramName, "SQ", -1, "");
        goto CloseBossCommunication;
    1
    /// Read configuration
    if (CConfiguration.usReadConfig (pcArgv[1], ulCurrentLineNumber, strCurrentTag))
        if (strCurrentTag.empty())
        {
            (void) usPrintError2Log (&BOSSCOMIdentifier, acProgramName, "SQ", -2, "No file found");
        else
            (void) usPrintError2Log (&BOSSCOMIdentifier, acProgramName, "SQ", -2, "Error in line %ld arround tag '%s'",
                                     ulCurrentLineNumber, strCurrentTag.c str());
        goto CloseBossCommunication;
```

#include <stdio.h>



How to control your equipment from FS?

Station QKR ("stqkr"): stqkr.cpp

C/C++-Code

```
#include <stdlib.h>
#include "fsshm.h"
#include "simple structured conf.hpp"
#include "meteo.hpp"
#include "rxmon.hpp"
#include "testequip.hpp"
                                                                       Module "fsmonitor" (Wettzell)
int main (int iArgc, char * pcArgv[])
                                                                  Communication with NASA FS boss
   BOSSCOM BOSSCOMIdentifier = NULL; /// BOSSCOMIdentifie
                                    /// "ip" of the fiel
   char acProgramName[6] = "stgkr";
                                         cProgramName =
   char acReceivedMessage[4096];
                                    /// acl
   CSimpleStructuredConf CConfiguration; /// CConf
   unsigned long ulCurrentLineNumber; /// ulCurrentLineNum
                                                      typedef long * BOSSCOM;
   std::string strCurrentTag;
                                    /// strCurrentTag =
                                                         unsigned short usOpenBossCommunication (BOSSCOM * pBOSSCOMIdentifier);
                                                         unsigned short usCloseBossCommunication (BOSSCOM * pBOSSCOMIdentifier);
   printf ("stgkr: Startup ... \n");
                                                         unsigned short usWaitForMessageFromBoss (BOSSCOM * pBOSSCOMIdentifier,
                                                                                                     char * pcProgramName,
   /// Open communication to NAS
   if (usOpenBossCommunication (&BOSSCOMIdentifier))
                                                                                                     char acReceivedMessage[4096]);
                                                         long lGetCommandIdentifierOfIncomingCommand (BOSSCOM * pBOSSCOMIdentifier);
       printf ("[ERROR] stgkr: Cannot open connection to N
                                                         long lGetIPCClassNumberForIncomingMessage (BOSSCOM * pBOSSCOMIdentifier);
       return 1;
                                                         long lGetNumberOfElementsInIncomingMessage (BOSSCOM * pBOSSCOMIdentifier);
                                                         unsigned short usAcknowledgeMessageProcessing (BOSSCOM * pBOSSCOMIdentifier);
                                                         unsigned short usPrintMessage2Log (BOSSCOM * pBOSSCOMIdentifier,
   /// Check program parameters
                                                                                               const char acProgramNameInput[6],
   if (iArgc != 2)
                                                                                               const char * pcFormat,
       (void) usPrintError2Log (
                                 OSSCOMIdentifier, acProc
                                                                                               ...);
       goto CloseBossCommunication;
                                                        unsigned short usPrintError2Log (BOSSCOM * pBOSSCOMIdentifier,
                                                                                             const char acProgramNameInput[6],
                                                                                             const char acFSErrorIdentCodeInput[3],
   /// Read configuration
                                                                                             int iErrorCode,
   if (CConfiguration.usReadConfig (pcArgv[1], ulCurrentLin
                                                                                             const char * pcFormat,
       if (strCurrentTag.empty())
                                                                                             ...);
                                                         unsigned short usReplyMessageToBoss (BOSSCOM * pBOSSCOMIdentifier,
           (void) usPrintError2Log (&BOSSCOMIdentifier, ac
                                                                                                 const char * pcFormat,
                                                                                                 ...);
       else
                                                         unsigned short usWriteSatEphemToFile(void);
           (void) usPrintError2Log (&BOSSCOMIdentifier, acProgramName, "SQ", -2,
                                                                            "Error in line %ld arround tag '%s'",
                                  ulCurrentLineNumber, strCurrentTag.c str());
       goto CloseBossCommunication;
```



C/C++-Code

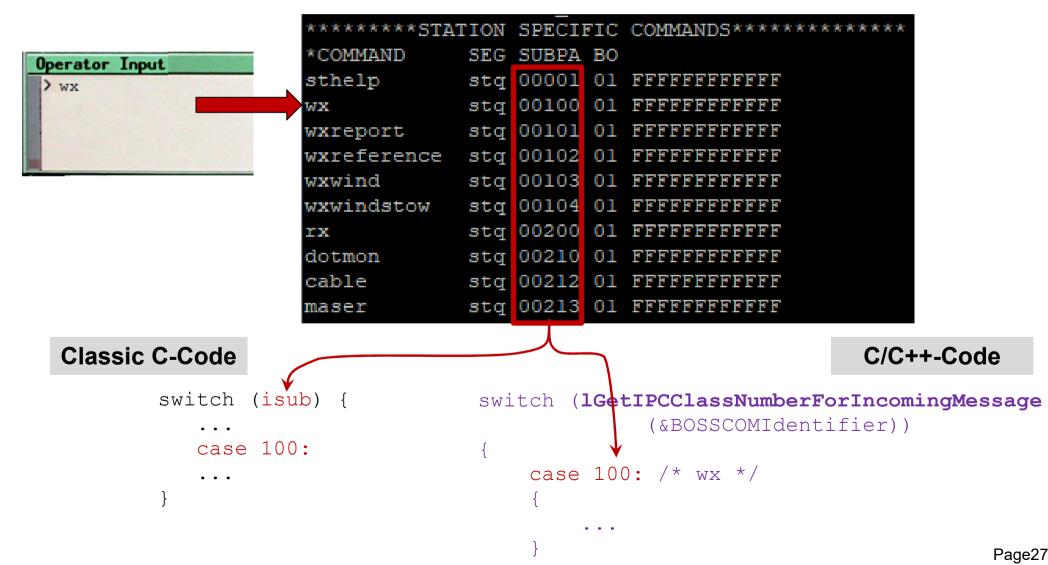
Station QKR ("stqkr"): stqkr.cpp

```
/// Start processing loop
   while (1)
   {
                                                            Wait for incoming
      /// Wait for incoming messages from boss
      if (usWaitForMessageFromBoss (&BOSSCOMIdentifier,
                                                            Orders and
                            acProgramName,
                            acReceivedMessage))
                                                            Receive command
                                                            and arguments
         continue;
      /// Switch between the different commands according to the class number
                                                            Identify
      switch (lGetIPCClassNumberForIncomingMessage (&BOSSCOMIdentifier))
                                                            command
         // Command "wx"
         case 100: /* wx */
                                                            Interprete and
                                                            Performe action
           11
         // Command "rx" and "rxall"
                                                            according to
         case 200: /* rx */
                                                            command
         case 201: /* rxall */
                                                            => Call function
         . . .
      if (usAcknowledgeMessageProcessing (&BOSSCOMIdentifier))
                                                            Prepare return
         continue;
                                                            values
CloseBossCommunication:
   /// Close communication to NASA FS boss
   if (usCloseBossCommunication (&BOSSCOMIdentifier))
   {
      printf ("[ERROR] stqkr: Cannot close connection\n");
      return 1;
   printf ("[ERROR] stqkr: While loop failed\n");
   return 1;
```



Station QKR ("stqkr")

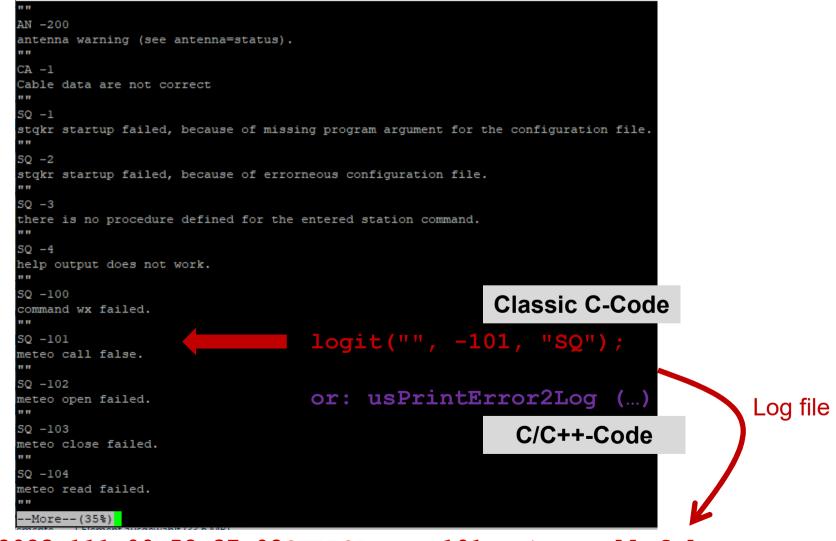
Sample "/usr2/control/stcmd.ctl":





Station QKR ("stqkr")

Sample "/usr2/control/sterr.ctl":



2023.111.09:58:37.02?ERROR sq -101 meteo call false. Page28



Difference 32-bit to 64-bit in station code

32-bit	===>	64-bit
long	===>	int

See:

https://nvi-inc.github.io/fs/misc/64-bit_conversion.html

For automatic conversion of station code see:

https://github.com/dehorsley/unlongify

But better (my personal opinion):

- Install a completely new computer with 64-bit Debian
- Install FSL10 or greater for 64-bit
- Copy your station code
- Go manually through your code and change it manually to int, where required (so that you can also validate address operations etc.)

===>

===>

Difference 32-bit to 64-bit in station code

52-DIL
long
long
/* from /usr2/fs/clib/skd util.c */
void skd wait (char name[5],
long ip[5],
unsigned centisec);
void skd_run (char name[5],
<pre>long ip[5]);</pre>
/* from /usr2/fs/clib/cls_util.c */
<pre>int cls_rcv long lIPCClassNumberForIncomingCommand,</pre>
<pre>char * acAnswerTextfer,</pre>
int length,
int * rtnl,
int * rtn2,
int msgflg,
int save);
<pre>void cls_snd long * lIPCClassNumberForIncomingCommand,</pre>
char * acAnswerTextfer,
int length,
int parm3,
int parm4);
<pre>void cls_clr long lIPCClassNumberForIncomingCommand);</pre>

22 hit

/* antcn main program starts here */
main()
{
int ierr, nrec, nrecr;
int dum = $0;$
int r1, r2;
int imode, i, nchar;
long ip[5], class, clasr;
char buf[80], buf2[100];

64-bit int	
* from /usr2/fs/clib/skd_util.c	
oid skd_wait (char name[5],	
int ip[5],	
unsigned centised	:)
oid skd_run (char name[5],	
char w.	

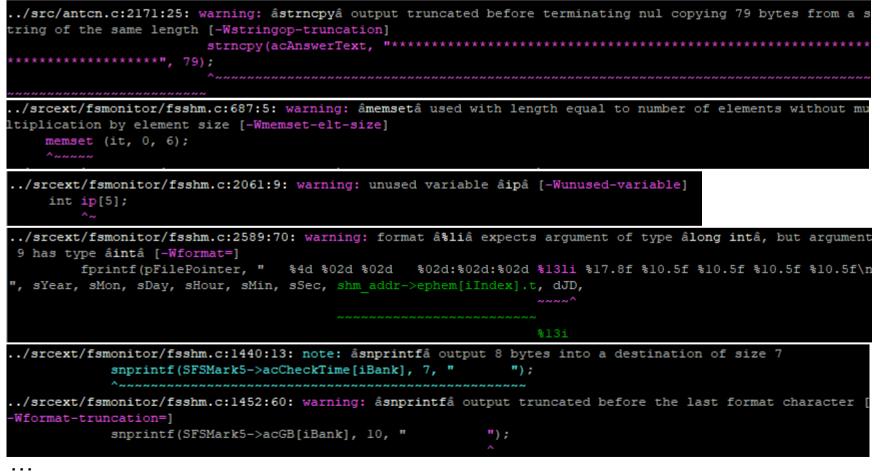
/* antcn main program starts here */
main()
{
 int ierr, nrec, nrecr;
 int dum = 0;
 int r1, r2;
 int imode,i,nchar;
 int ip[5], class, clasr;
 cnar buf[80], buf2[100];



Difference 32-bit to 64-bit in station code

32-bit	===>	64-bit
long	===>	int

Expect more warnings



→ Take warnings seriously and fix all of them!

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TOW2025 - Seminar

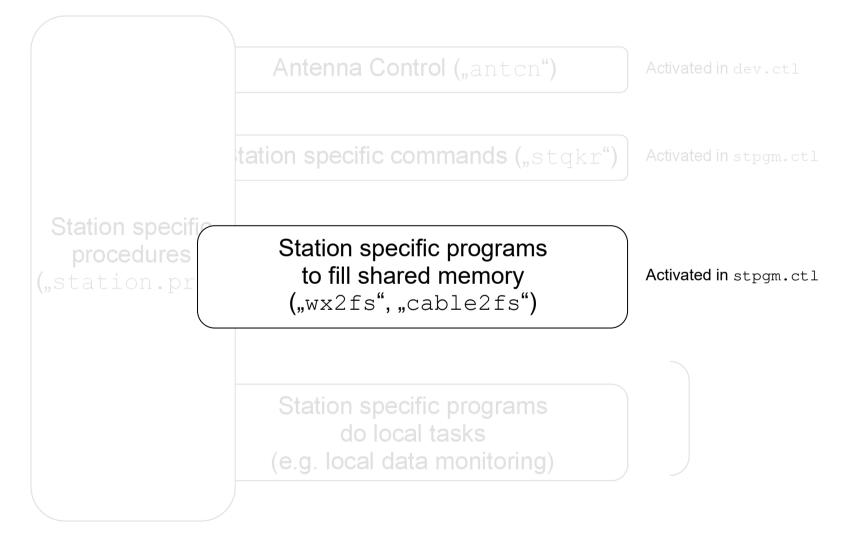
FS Station Code

What about FS? What does a station has to offer to the FS? How to control your antenna from FS? How to control your equipment from FS? **How to fill data sets of the FS?**

How to add functionality to the FS? How to extend number of parallel devices? How to combine functionalities to the FS?



How to fill data sets of the FS?





How to fill data sets of the FS?

Sample for an own meteorological sensor

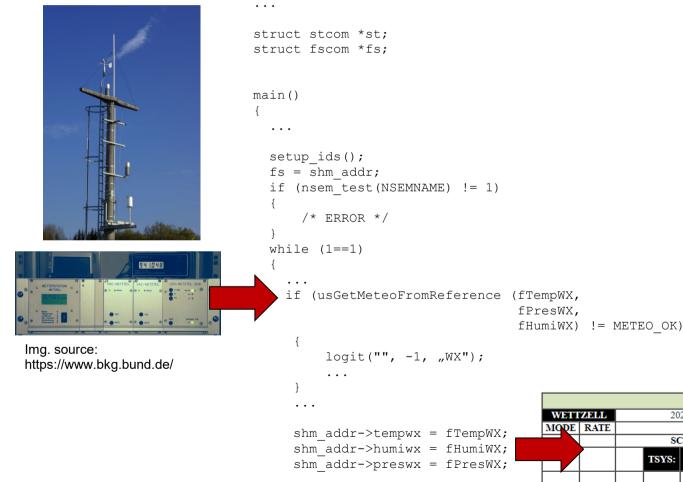
```
/* Include section similar to stgkr.c */
. . .
struct stcom *st;
struct fscom *fs;
main()
{
  . . .
  setup ids();
  fs = shm addr;
  if (nsem test(NSEMNAME) != 1)
  {
      /* ERROR */
  }
  while (1==1)
  {
    . . .
    if (usGetMeteoFromReference (fTempWX,
                                    fPresWX,
                                    fHumiWX) != METEO OK)
     {
         logit("", -1, "WX");
          . . .
     }
     . . .
     shm addr->tempwx = fTempWX;
     shm addr->humiwx = fHumiWX;
     shm addr->preswx = fPresWX;
      . . .
}
```



How to fill data sets of the FS?

Sample for an own meteorological sensor

/* Include section similar to stqkr.c */



. . .

	System Status Monitor										
WETTZELL	20	23.111.2	3:55:15	UT		TEMP	10.8	2000	+472	SL	EWING
MODE RATE		0	7:15:00	NEXT		HUMID	53.9	RA	20h 02m	10.42s	
	so	HED=	none	LOG=	station	PRES	942.2	DEC	47d 25m	L	(2000)
	TSYS:	IFA	IFB	IFC	IFD	CABLE	0.006370	AZ	59.7837	EL	39.7989
		37	55	132	-47	WIND	5.04	DIR	74		
NO CHECK: 1X											



How to add functionality to the FS?

Control files /usr2/control/stpgm.ctl

	* Put site-specific programs here that should * be started by the Field System.
FS	* antcn should not be here.
	erchk x xterm -name erchk -e erchk &
programs	
	<pre>scnch x xterm -name scnch -e 'fsclient -n -w -s grep /!*scan_check' &</pre>
-	wx2fs n wx2fs > /dev/null 2> /dev/null &
Station	stąkr n stąkr /usr2/st/control/stąkr.conf &
nrograme	cable2fs n cable2fs /usr2/st/control/cable2fs.conf &
programs	patch_mark6.sh x /usr2/st/bin/patch_mark6.sh init:192.168.1.1:14 &

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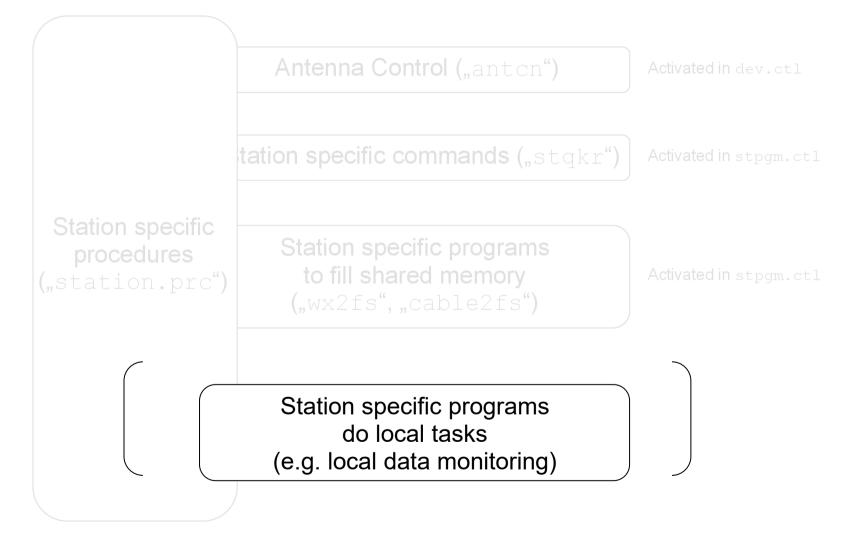
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How to add functionality to the FS?

Station-specific programs





How to command the FS in your code?

Command injection

/usr2/fs/bin/inject_snap

/usr2/fs/bin/inject_snap -w log

→ Output of current log filename e.g. log/station

/usr2/fs/bin/inject_snap '" Test' Send comment to FS



How to read answers from the FS in your code?

Command reply catching ("streamlog")

FS Display Server to get log messages



"streamlog" is recommended for FS 10.2 or greater to get log messages.

https://github.com/nvi-inc/fs/blob/main/misc/display_server.md



How to read answers from the FS in your code?

Command reply catching ("streamlog")

/usr2/fs/bin/fsclient

/usr2/fs/bin/fsclient -n

- → Get all log messages on standard out
- /usr2/fs/bin/fsclient -s -n
- ➔ Get all log messages on standard out inclusively some historic lines

2	:	4	6	:	4	7	;	rx=	d	e	W	a	1

/rx/dewar,NOK,19.00,0.00,292.00,1.0900e+01 15:14:14;-help 15:14:14?ERROR sp -4 Unrecognized name (not a function or procedure). 15:17:12;log 15:17:12/log/station 15:19:02:wx L5:19:02#stgkr#wx/Used meteo site: GOW Meteo Database (Wetterstation Wettzell) 15:19:02#stqkr#wx/Height of pressure sensor: 656.025 m 15:19:02/wx/10.30,937.80,52.00 15:20:51;" Test 5:29:51;wx 15:29:51#stgkr#wx/Used meteo site: GOW Meteo Database (Wetterstation Wettzell) 15:29:51#stqkr#wx/Height of pressure sensor: 656.025 m 15:29:51/wx/9.90,938.00,53.60 L5:29:55:wx 15:29:55#stqkr#wx/Used meteo site: GOW Meteo Database (Wetterstation Wettzell) 15:29:55#stqkr#wx/Height of pressure sensor: 656.025 m L5:29:55/wx/9.90,938.00,53.60

==> pipe the output to a program which can read it as standard in so that you can use it in other programs or scripts e.g.

fsclient -s -n | grep "wx"

End with Ctrl - C

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How to add functionality to the FS?

SNAP system calls

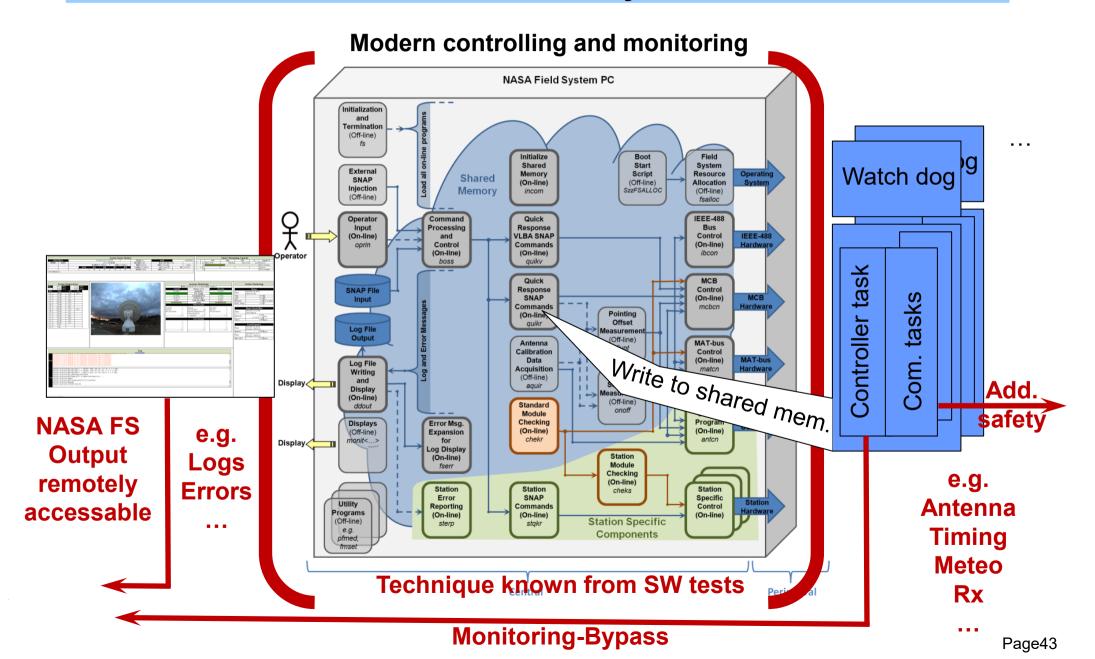
Sample SNAP file of schedule r4999wz

scan_name=140-1933,r4999,wz,60,60
source=3c418,203837.03,511912.7,2000.0,ccw
setupsx
!2021.140.19:33:07
preob
!2021.140.19:33:17
<pre>sy=cmd2flexbuff.py net2file=open:/raid/r4999wz/r4999_wz_140-1933,n ;</pre>
data_valid=on
midob
!2021.140.19:34:17
data_valid=off
sy=cmd2flexbuff.py net2file = close
postob



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Sample 2 DBBCs:

/usr2/control/dbba2.ctl
→ Commands
• • •
dbbc2=power=1
• • •
fila10g2=arp off
•••

But what if you have more than the allowed standard devices?

Attention ... here comes a hack!!!



But what if you have more than the allowed standard devices?

socat - Multipurpose relay
e.g. socat TCP-LISTEN:142,fork,reuseaddr TCP:192.168.1.1:142

Extend station.prc

```
define mydev3 000000000x
sy=/usr2/st/bin/myscript_device3.sh > /dev/null 2> /dev/null
enddef
```

Script myscript_device3.sh

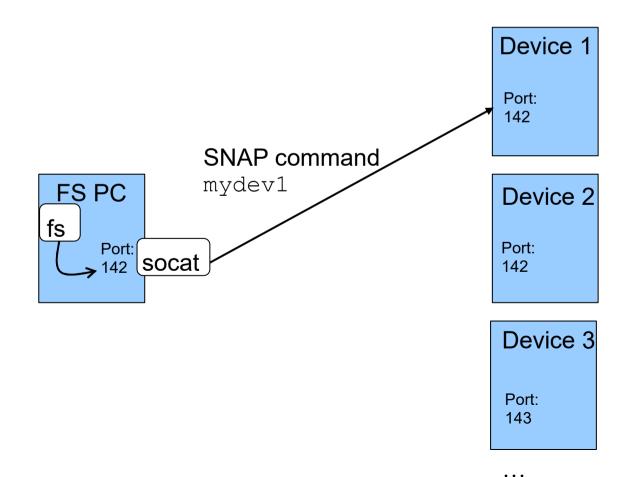
```
socat_basic_call="socat TCP-LISTEN:140,fork,reuseaddr TCP:"
# Kill previous patching
COMMAND="ps ax | grep \"${socat_basic_call}\" | grep -v grep | grep -o -E \"^[]*[0-9]+\" | tr '\n' ' '"
SOCAT_PIDS=`eval $COMMAND`
if [[ -n $SOCAT_PIDS ]]; then
    kill -9 $SOCAT_PIDS
    #echo -e "Killing processes with \"kill -9 $SOCAT_PIDS\""
fi
# Start patching of communication with socat
SOCAT_CALL="${socat_basic_call}192.168.1.1:143 > /dev/null 2> /dev/null &"
eval $SOCAT_CALL
```



But what if you have more than the allowed standard devices?

socat - Multipurpose relay

e.g. socat TCP-LISTEN:142, fork, reuseaddr TCP:192.168.1.1:142

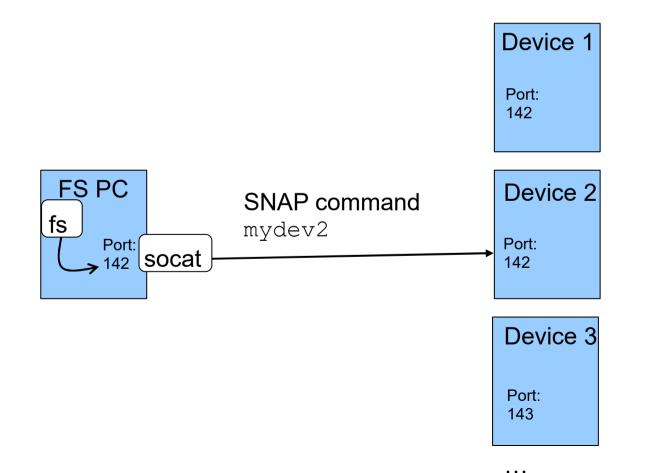




But what if you have more than the allowed standard devices?

socat - Multipurpose relay

e.g. socat TCP-LISTEN:142, fork, reuseaddr TCP:192.168.1.2:142

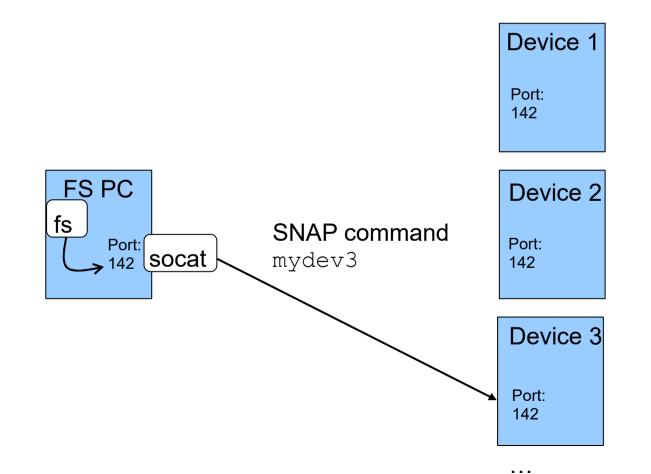




But what if you have more than the allowed standard devices?

socat - Multipurpose relay

e.g. socat TCP-LISTEN:142, fork, reuseaddr TCP:192.168.1.3:142

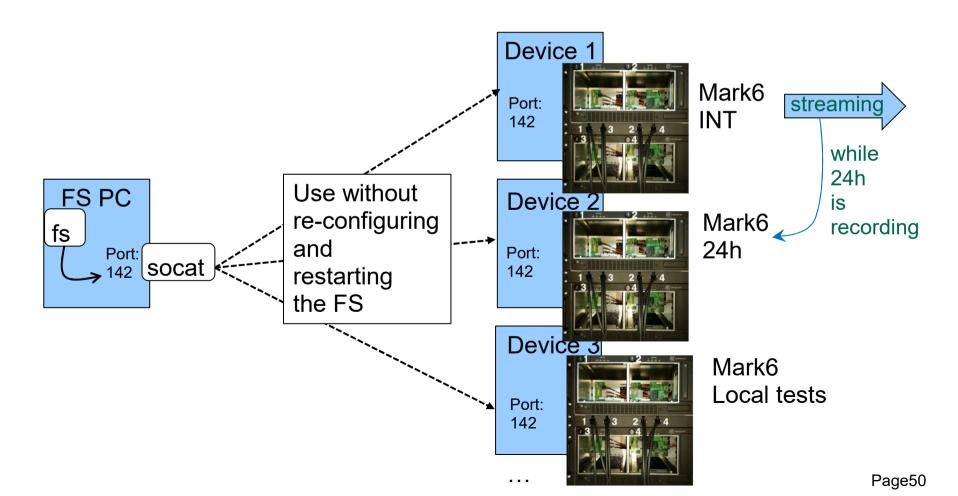




But what if you have more than the allowed standard devices?

socat - Multipurpose relay

e.g. socat TCP-LISTEN:142, fork, reuseaddr TCP:192.168.1.1:142



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How to combine functionalities to the FS?

Station-specific programs

	Antenna Control ("antcn")	Activated in dev.ctl
	tation specific commands ("stqkr")	Activated in stpgm.ctl
Station specific procedures ("station.prc")	Station specific programs to fill shared memory ("wx2fs", "cable2fs")	Activated in stpgm.ctl
	Station specific programs do local tasks (e.g. local data monitoring)	



How to combine functionalities to the FS?

Procedures in "station.prc"

define	preob	23111184450x
if=cont	cal,,!*+4s	
if=cont		man
onsourc	e	
"caltsy	5	
check=*		
enddef		
define		23111184501 x
onsourc		
antenna	=status	
WX		
rx=dewa	r?	
cable		
ifa		
ifb		
ifc		
ifd		
bbc01		
bbc05		
bbc09		
bbc13		
mk5c_mo	de	
!+1s		
	setcl adapt &	
enddef		
define	postob	23111184541 x
dotmon		
sy=lgpu	t2 `lognm` &	
enddef		

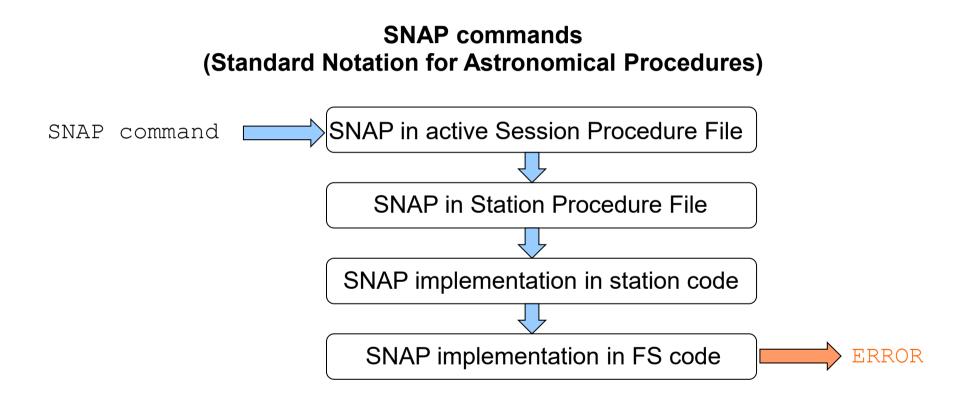
define	casa	00000000000				
check=						
source=casa,232324.8,+584859.,2000.0,null						
enddef						
define	safepos	00000000000				
antenna=safepos						
enddef						

calon caloff

. . .



How to combine functionalities to the FS?





FS Station Code

Thank you ...