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# Turning the Haystack-37m Telescope into a Multi-User Research Instrument

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## **Example Projects**

Demonstrating telescope capabilities



## Background

#### Haystack 37m Telescope

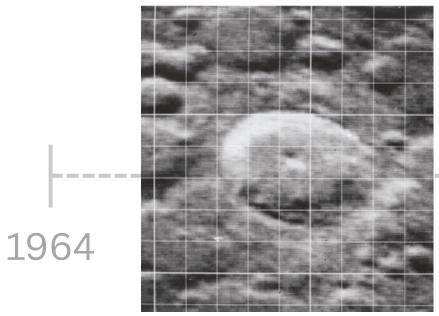
- 37-meter, radome-enclosed radio dish first constructed in 1964
- Rebuilt in 2010–2014 to have a significantly-improved dish surface accuracy of <0.1 mm</li>
- Slewing speed, surface precision, and pointing accuracy result in efficient, sensitive observations at frequencies up to ~230 GHz in the winter
- Current work is focused on instrument characterization and demonstration of scientific capabilities



Haystack Telescope Radome | Credit: The Center for Land Use Interpretation

# History of Astronomy with the 37m

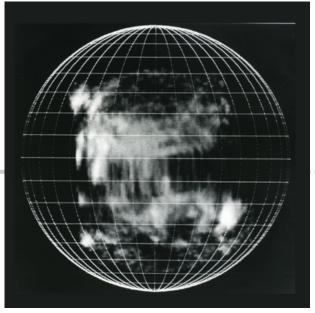
#### **Selected Astronomical Achievements**



Radar map of the lunar crater Tycho, published in 1974

1960s

Informed selection of Apollo landing sites



Venus's surface features from radar interferometry, 1966

1960s

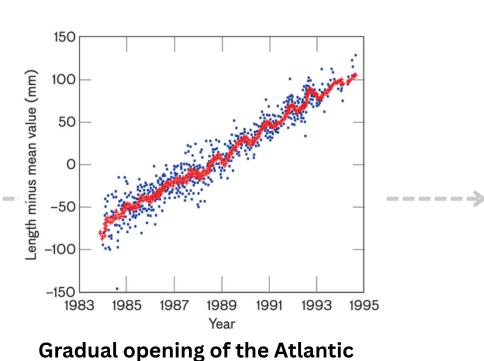
Created first radar maps of Venus' surface with separate northern and southern hemispheres



Early VLBI Recorder

1960s-70s

Leader in the establishment of Very Long Baseline Interferometry (VLBI)



Creation and development of Geodetic VLBI

Ocean floor

1970s-90s

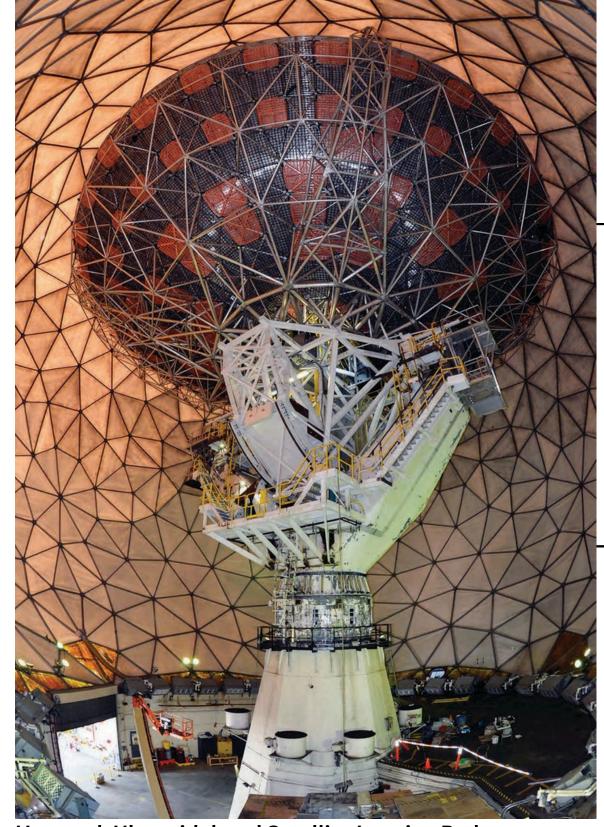
## **Project Goals**

#### **Motivation**

- If fully equipped, the Haystack 37m Telescope would be one the two most sensitive millimeter wave instruments in the continental United States.
- Extremely useful instrument for a variety of different research fields
- Near-future goal is to make this telescope available for the astronomical community for research and education
- However, lacking a user friendly control system

#### Goal

Create a more capable system for the Haystack 37m Telescope to turn it into a multi-user research instrument



Haystack Ultrawideband Satellite Imaging Radar Credit: Lincoln Laboratory Website



# OG Contro O2 System & User Interface

Terminal

Laplace

TCS: Telescope Control System

## Old Control Signal Chain

- Each blue box is a separate computer with distinct capabilities and roles within the signal chain
- Telescope operation requires that these computers share real time data
- RF Signal Chain

  GPU Host

  gpu1080

  Backend
  Software

  copy process

  Terminal

  Pointing and
  Calibration Scripts

  Terminal

  Calibration Scripts

  Terminal

TCS DB

**TCS** 

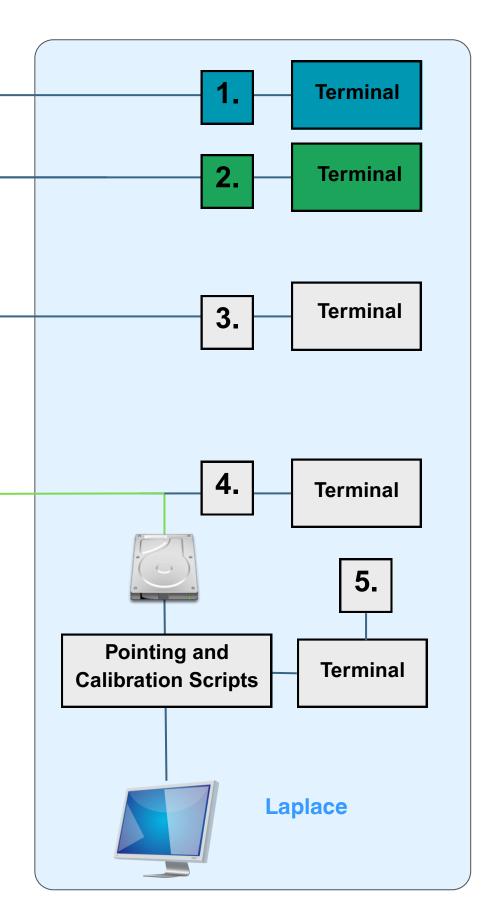
**TCS Client** 

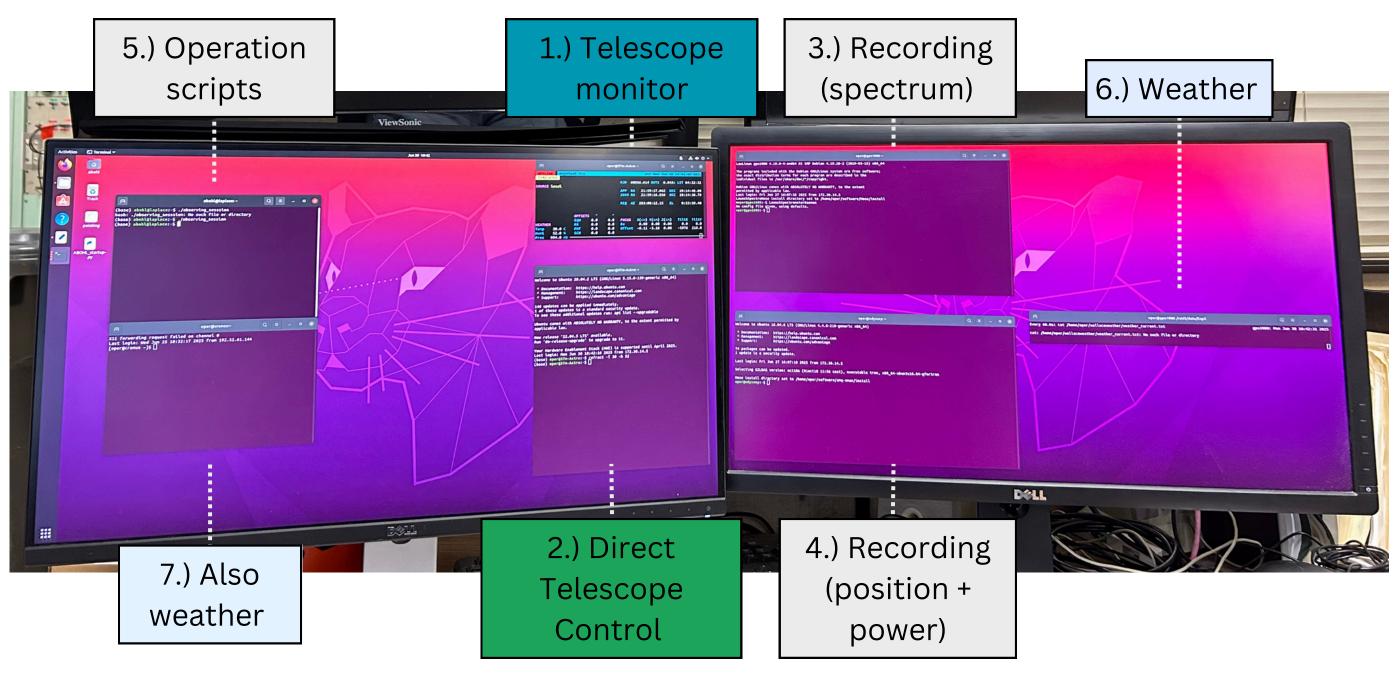
(Shell)

- However, data cannot be shared directly between shells.
- Data coordinated via shell script that moves mouse cursor between different terminal windows

Cannot touch mouse during telescope operation!

#### Old User Interface

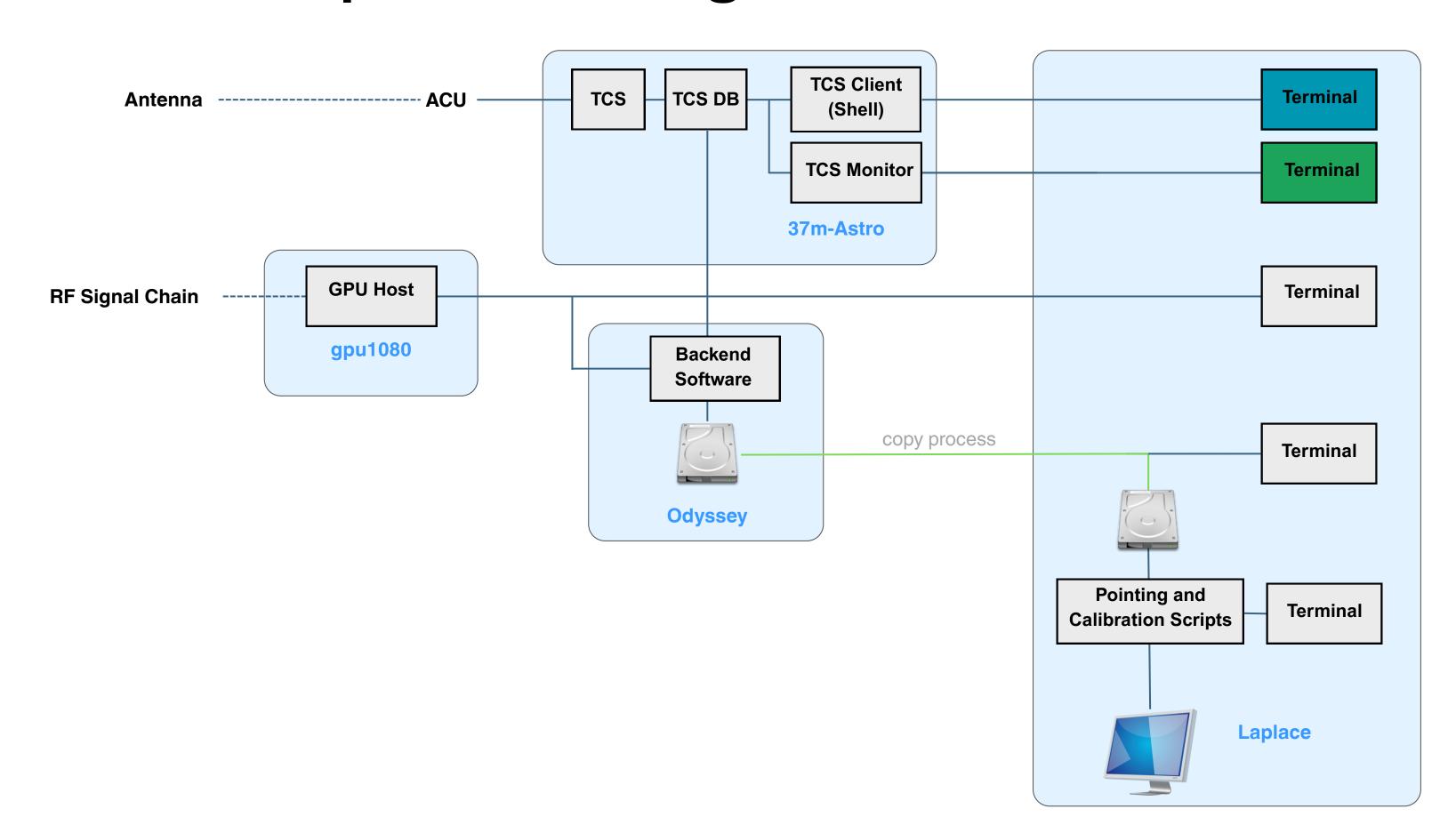




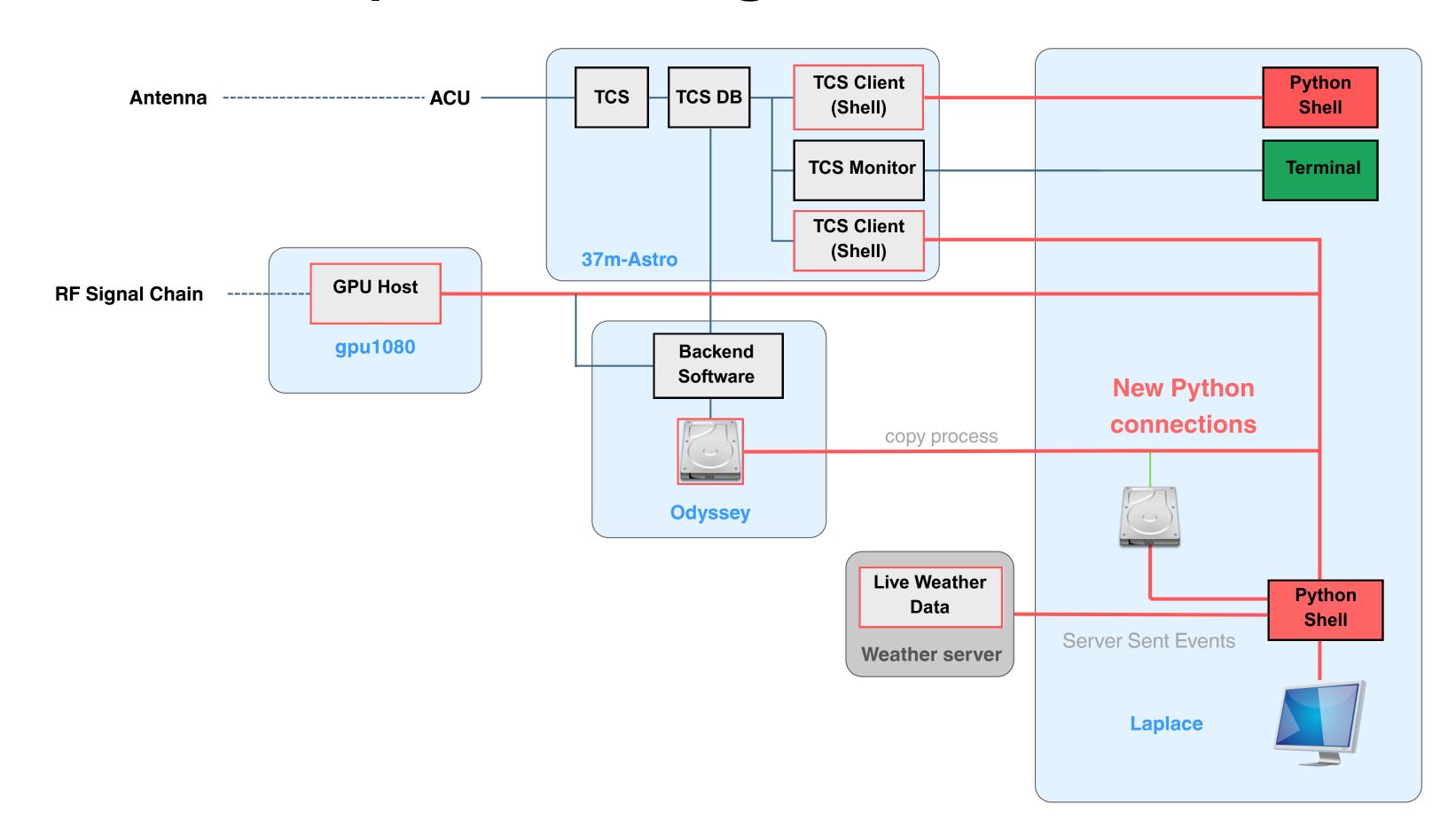
- Visually cluttered
- Shells not communicating
- Cannot touch mouse during operation.



# Old Telescope Control Signal Chain



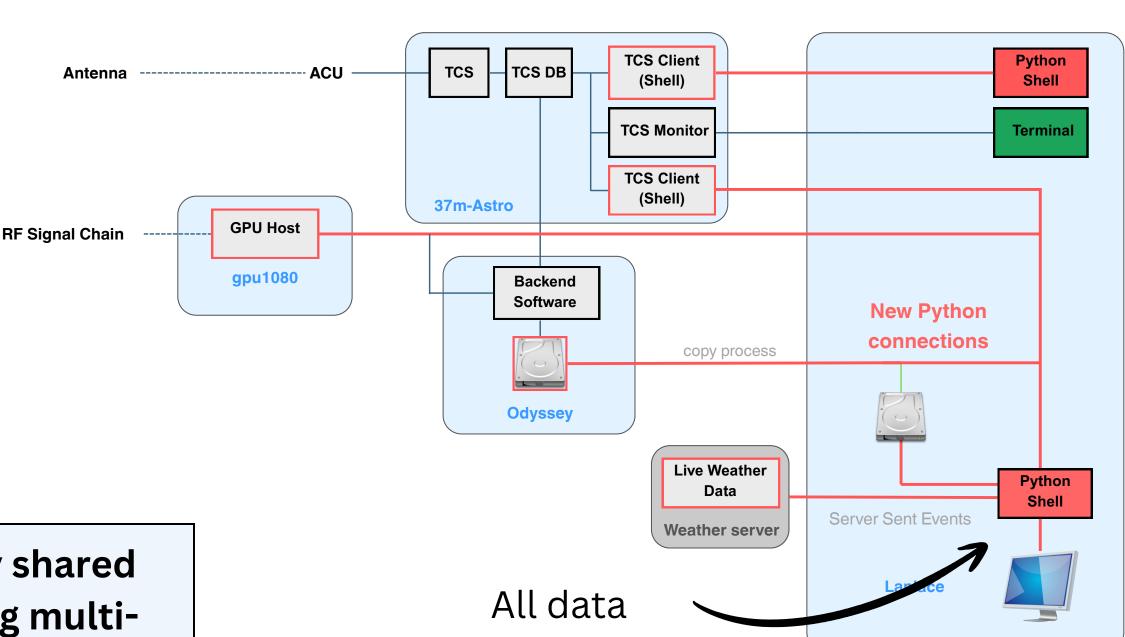
## New Telescope Control Signal Chain



# New Telescope Control Signal Chain

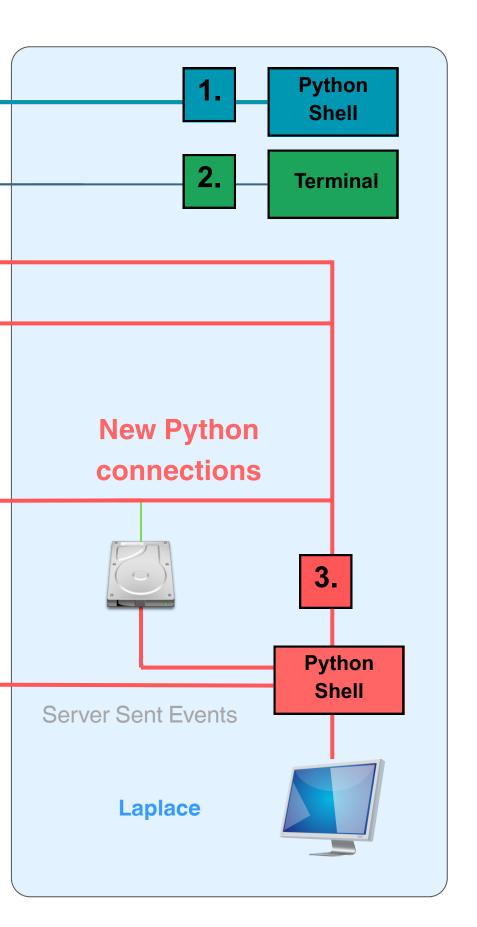
- Red represents a new Python connection
- One Python shell in Laplace communicates simultaneously with other three computers
- All data is now in one central location

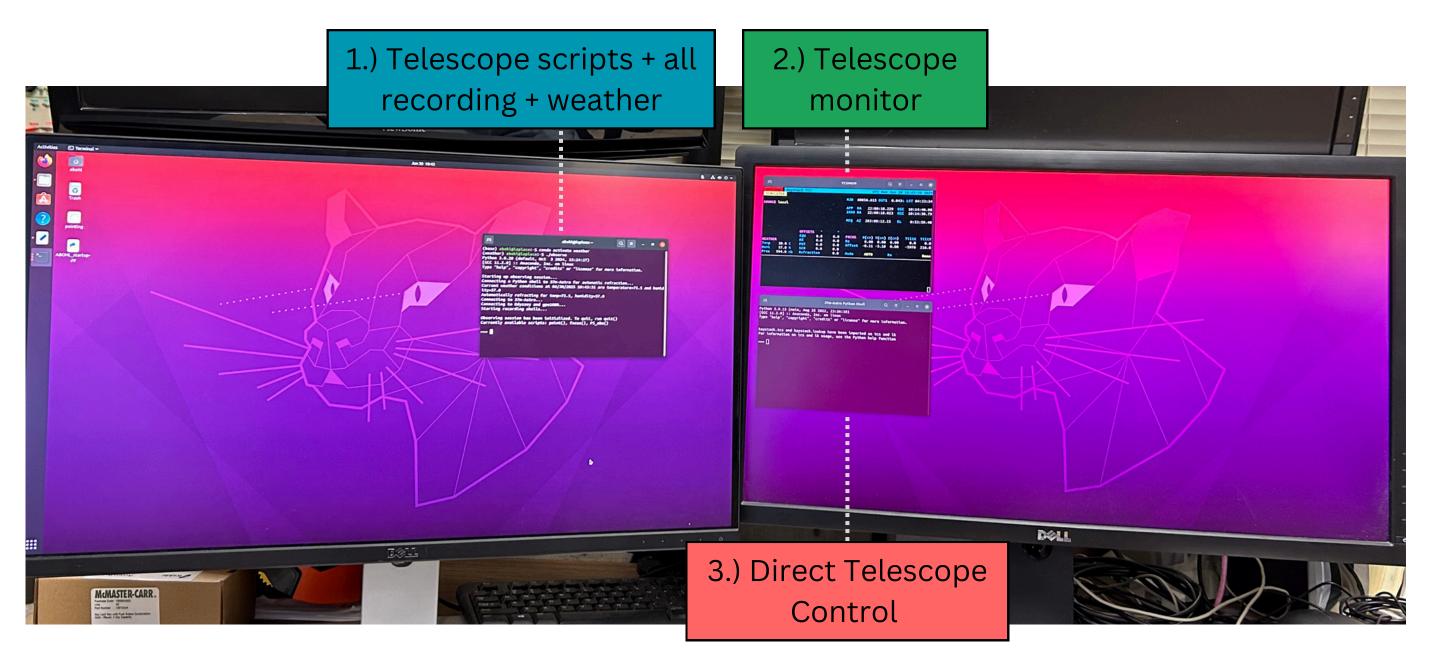
 Real-time data can now be easily shared between computers, streamlining multicomputer processes and enabling new metadata collection



consolidated here

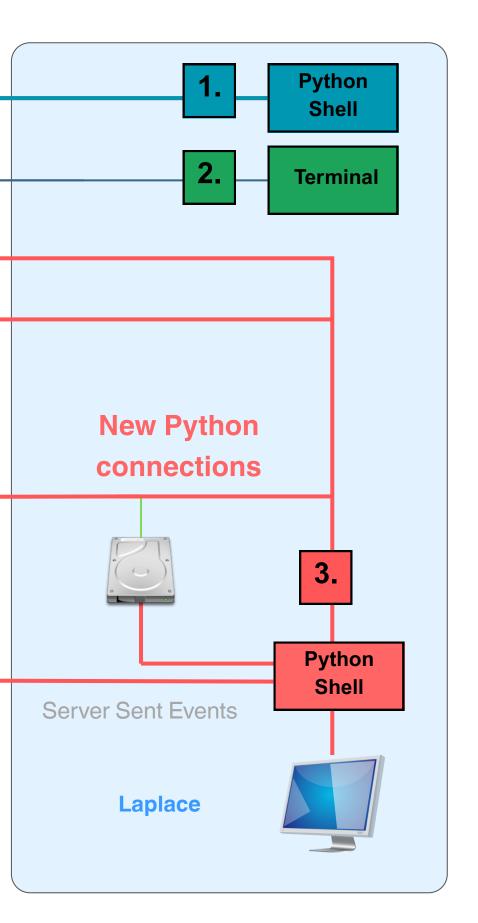
#### **New User Interface**

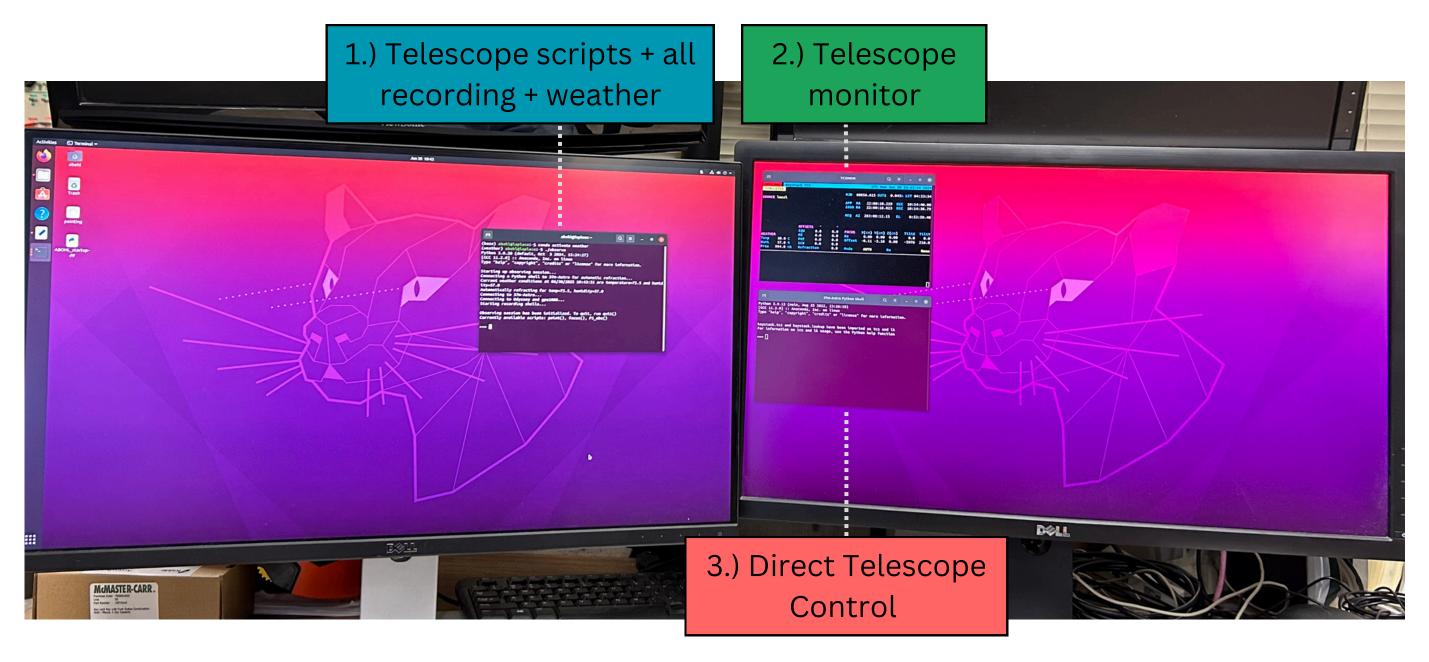




- Less visual clutter
- Real-time data sharing streamlines multi-computer scripts
- Allows for metadata collection

#### **New User Interface**





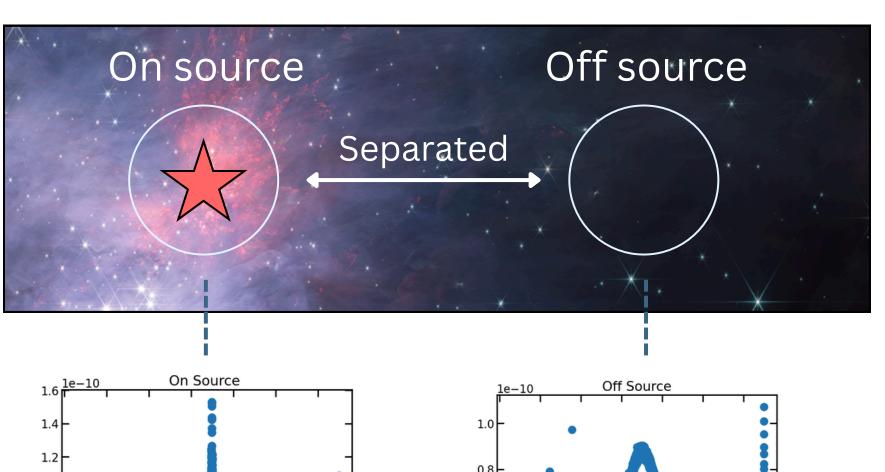
- Less visual clutter
- Real-time data sharing streamlines multi-computer scripts
- Allows for metadata collection

...And you can touch the mouse!

## Computers Working Together: Raster Map

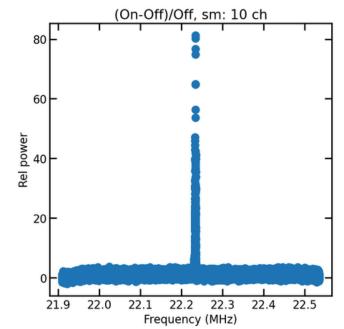
1000

Frequency (MHz)



#### **Position Switching**

- To remove atmospheric contributions, take observations "on-source" and "offsource"
- This is called position switching



 Subtract the off-source from the on-source and normalize to obtain spectra

Subtract, normalize

Frequency (MHz)

# Computers Working Together: Raster Map

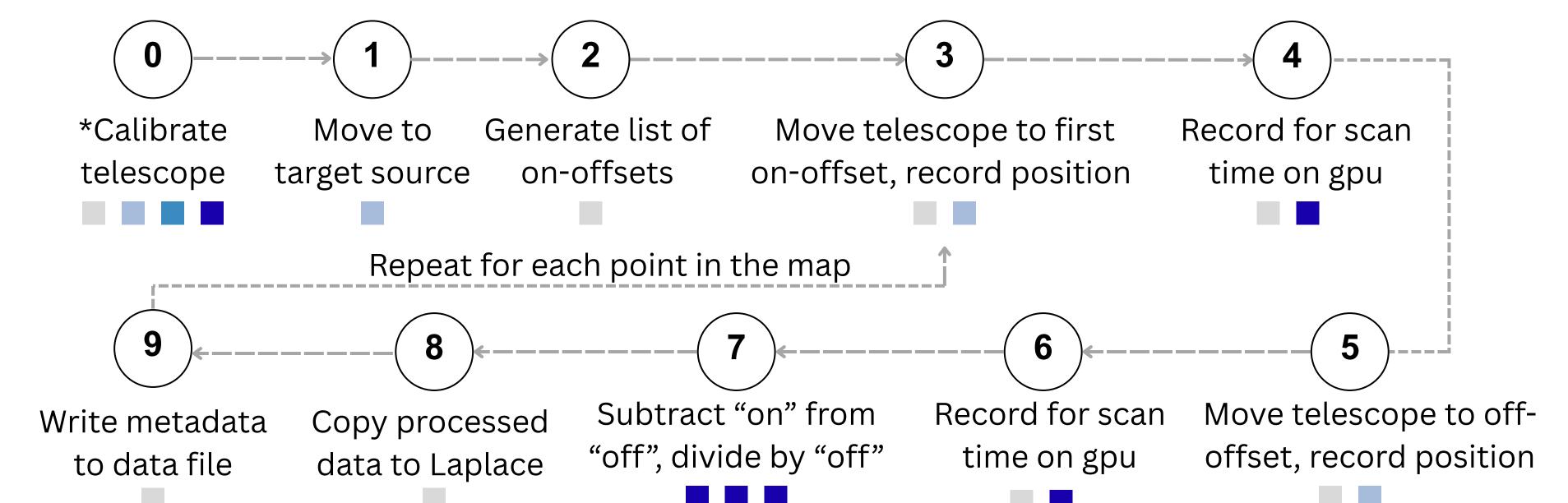
**Parameters**: target source, raster map dimensions, off-source offset, scan time, smoothing

# **Computer key:**Laplace

37m-Astro

Odyssey

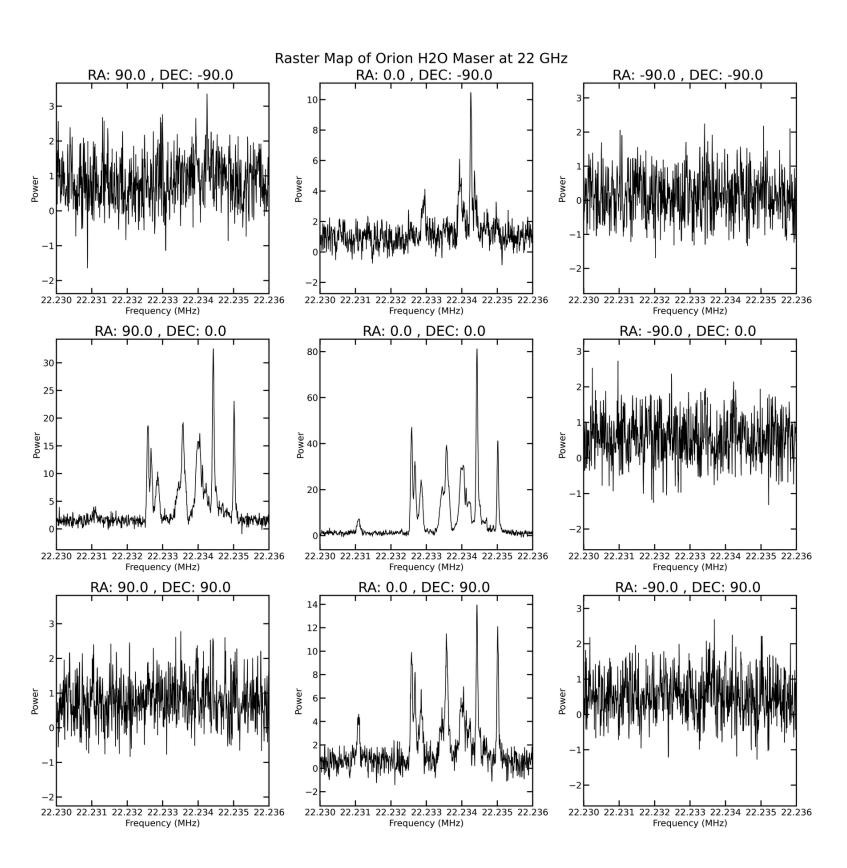
gpu1080



# Computers Working Together: Raster Map

#### **Results:**

- Result: spectra that can be processed to obtain a raster map
- Metadata is required for such maps
   need to know where on the sky each data-point was taken
- This functionality was not available prior to the creation of the new control system



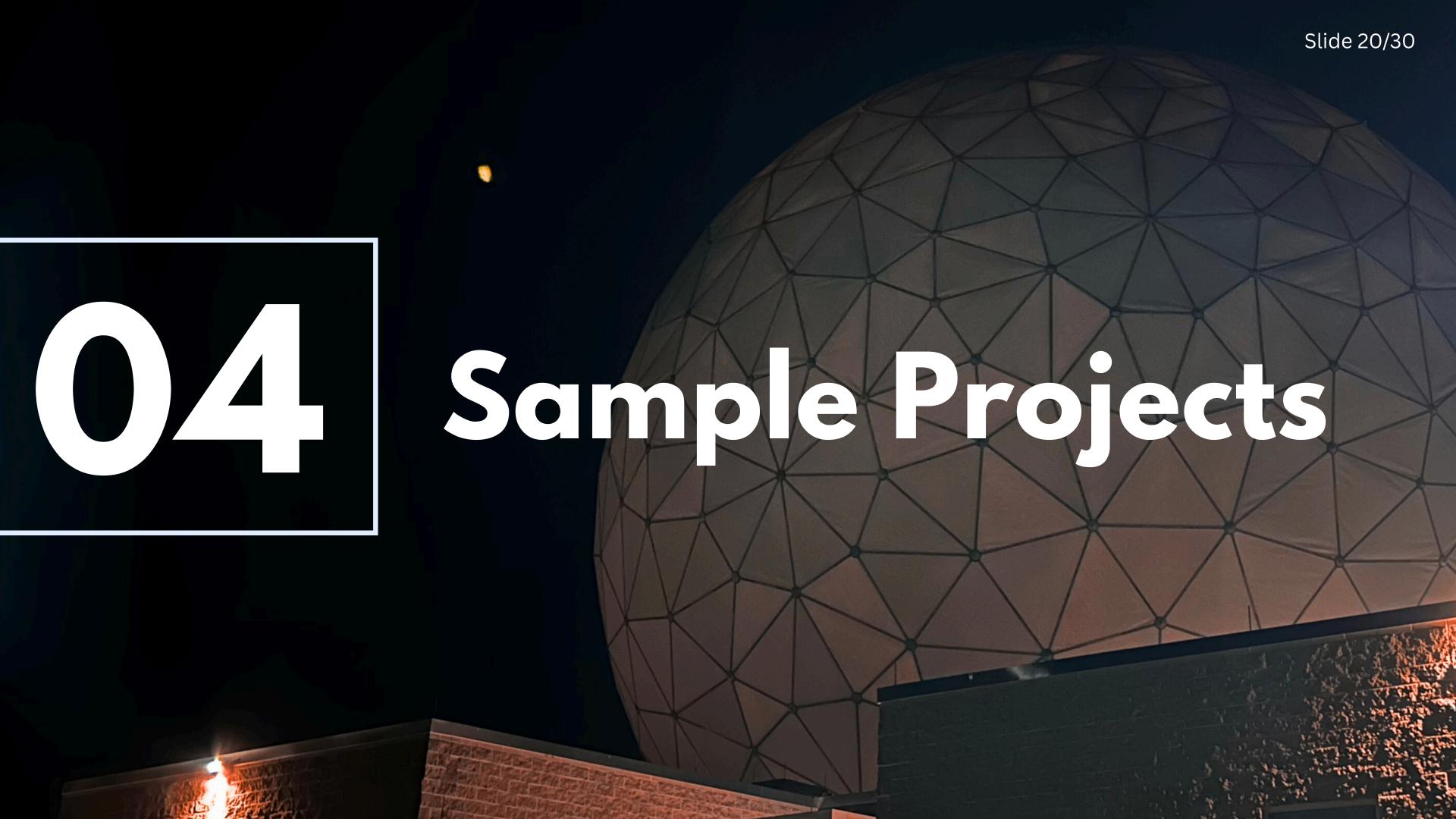
## **Python Libraries Created**

#### **Primary Observing Script**

• **observing\_session.py**: Creates an interactive observing session from which calibration and observing scripts can be run. Observing session maintains persistent connections with 37m-Astro, Odyssey, and gpu1080, sharing data between computers.

#### Haystack-Python Module

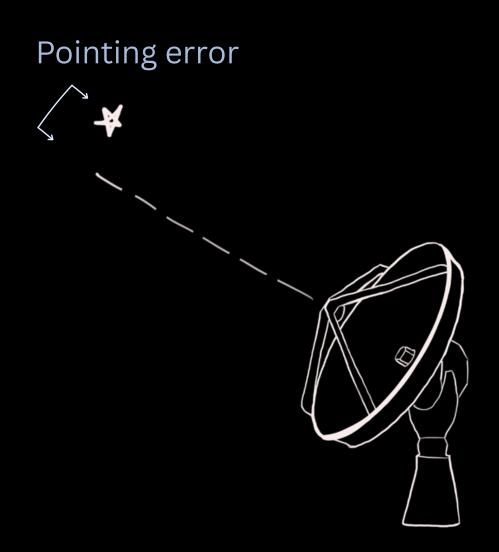
- **connections.py**: Facilitates rapid connections between computers; Continually updates a data log in the background of observing sessions
- plotting.py: Processes and plots data as it is taken by the telescope
- tcs\_functions.py: Contains helper scripts for observing\_session.py, including position tracking, file transfers, and data recording
- weather.py: Constantly monitors live weather data in the background of observing sessions, adjusting telescope refraction when weather changes exceed a given threshold



# Pointing Scans: Background

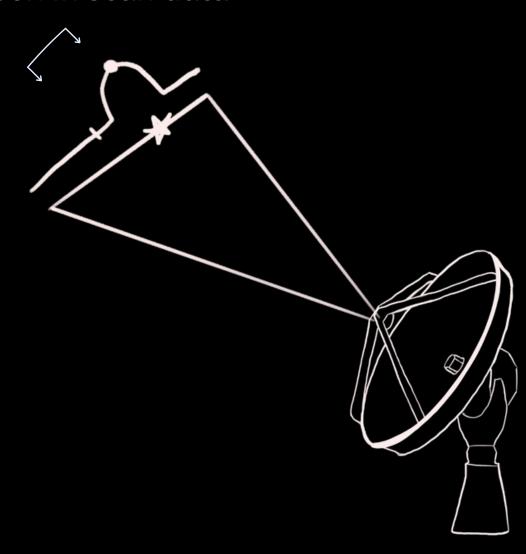
#### What is a pointing scan?

- Telescope must be calibrated to ensure it is pointing exactly at the target source
- Pointing the telescope at a source, then scan across in azimuth and elevation
- Find the distance between the data peak and the center of the scan, adjust pointing



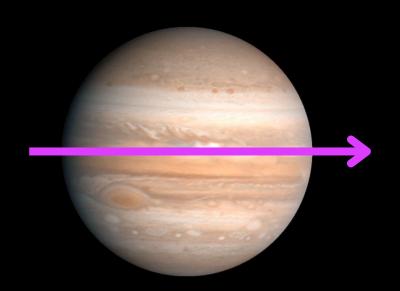
Un-calibrated telescope pointing

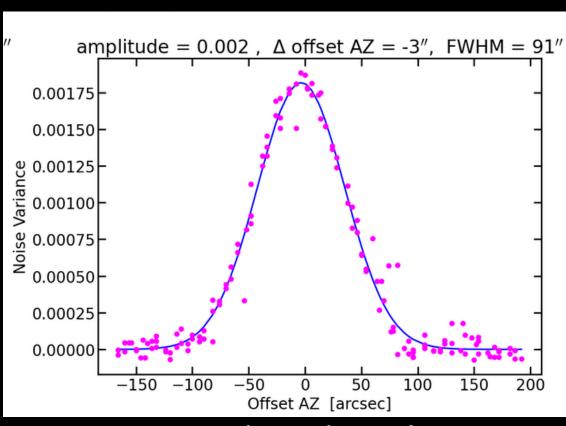
Pointing error as seen in scan data



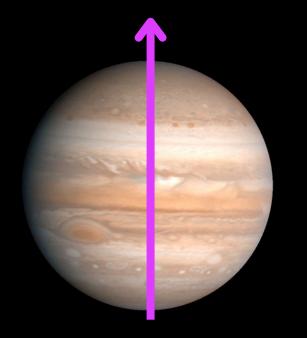
Scan across target source, adjust pointing

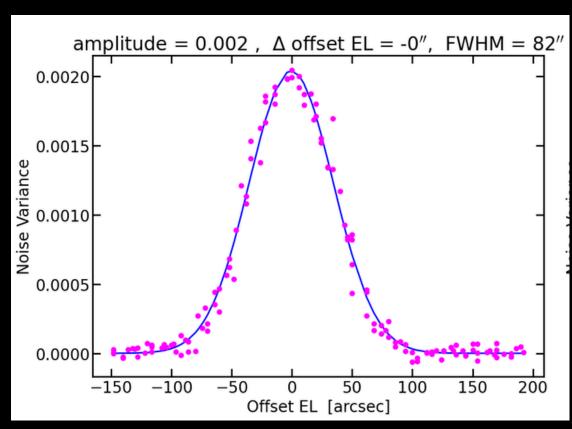
## Pointing Scans: Jupiter





Scan in azimuth



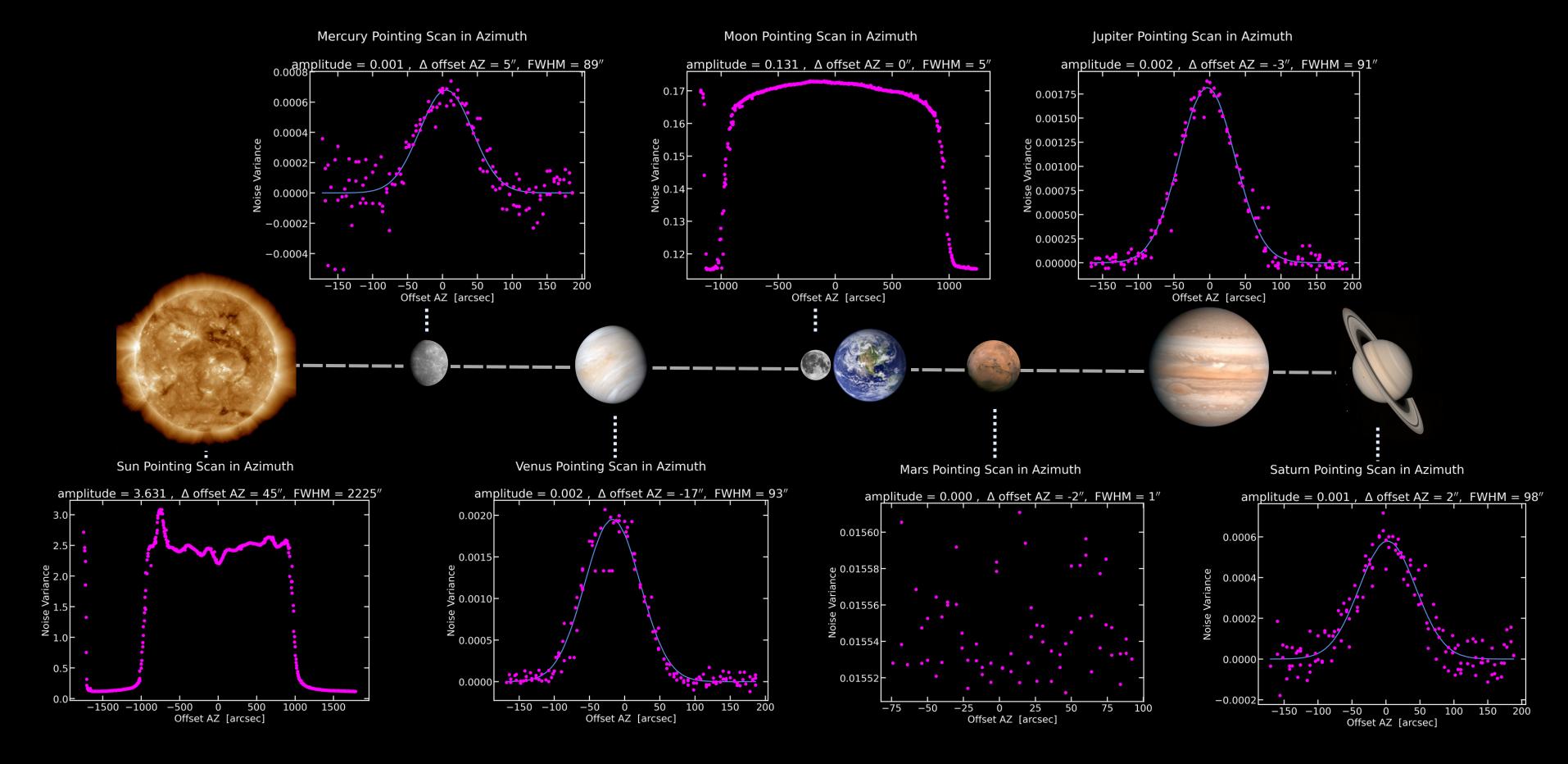


Scan in elevation

- Example pointing scans of Jupiter
- Scans in both azimuth and elevation
- AZ Δ offset = -3
   arcsec, EL offset = 0

   arcsec
- Note, the delta offset is small in both scans, has been calibrated

# Pointing Scans: Solar System Gallery



## Pointing Scans: Temperature Ratios

#### Method

- Can easily calculate the relative temperature between planets using pointing scans by
  - 1. Calculate the signal amplitude of the pointing scans
  - 2. Calculate angular cross section of each planet using distance to Earth and planet radius
  - 3. Calculate relative temperature using

$$T_{sig,planet} = \frac{\Omega_{planet}}{\Omega_{beam}} T_{surf,planet} \longrightarrow \frac{T_{surf,planet1}}{T_{surf,planet2}} = \frac{T_{surf,planet1}}{T_{surf,planet2}} \frac{\Omega_{planet2}}{\Omega_{planet1}}$$

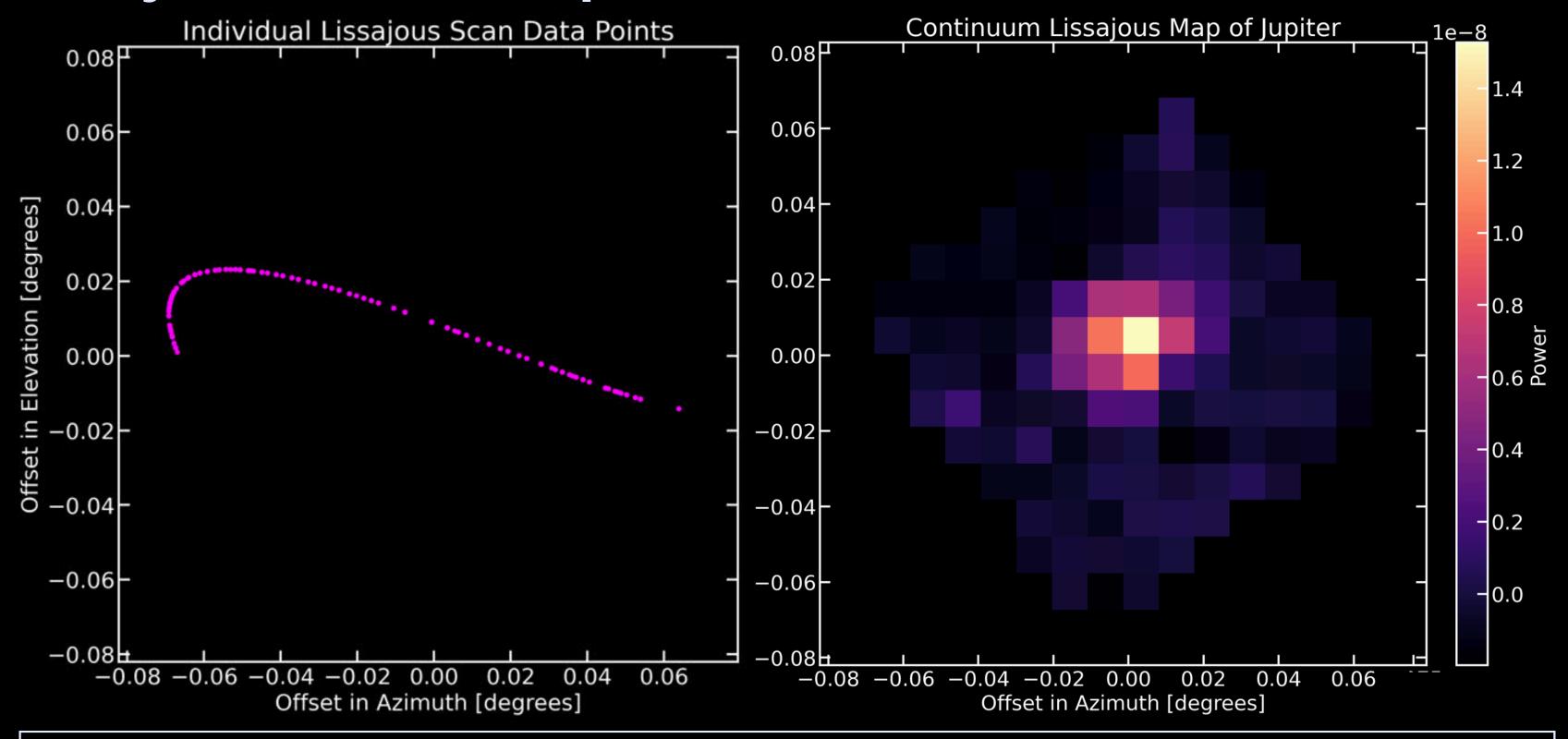


Takeaway:
Straightforward method
that obtains
results
consistent with
the literature

#### Results

Name	Temp Relative to Venus	Brightness Temp. (K)
Venus	AZ: 1.00 EL: 1.00	AZ: 480 EL: 480
Mercury	AZ: 0.407 EL:0.515	AZ: 196 EL: 247
Jupiter	AZ: 0.526 EL: 0.440	AZ: 252 EL: 211

## Lissajous Raster Map

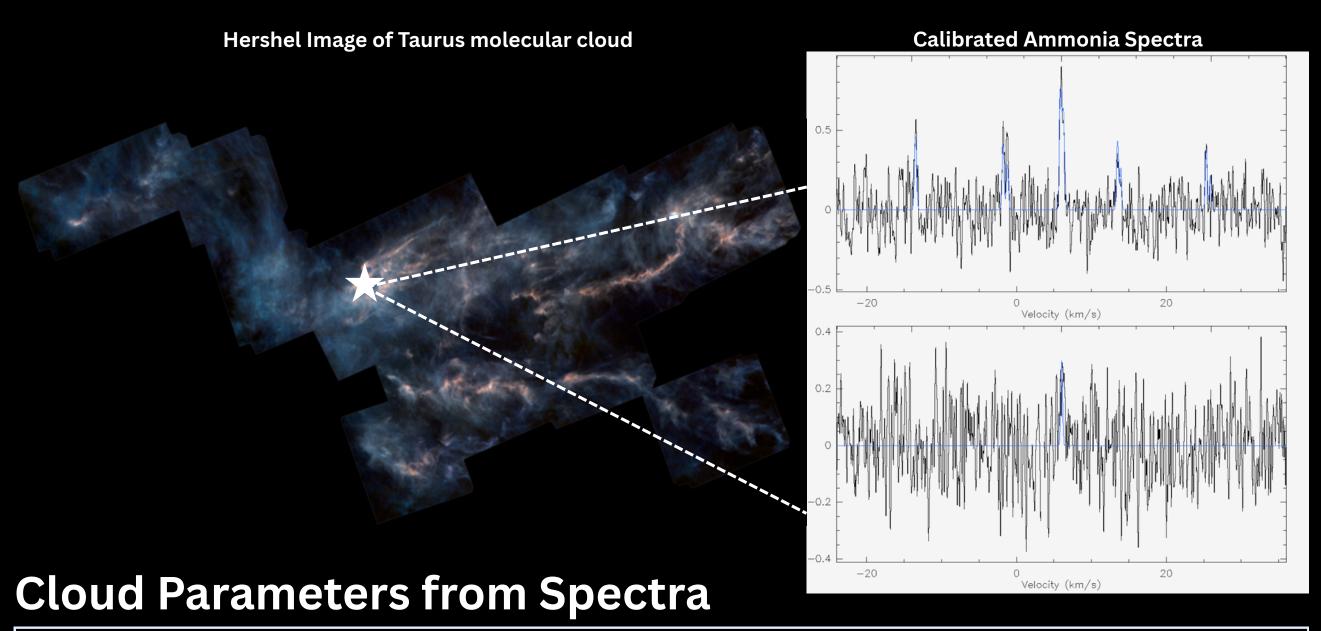


- Lissajous scans across target source in spirals
- Re-grid continuum data to obtain map

## Ammonia Spectra from TMC 1

#### **Astro-Chem**

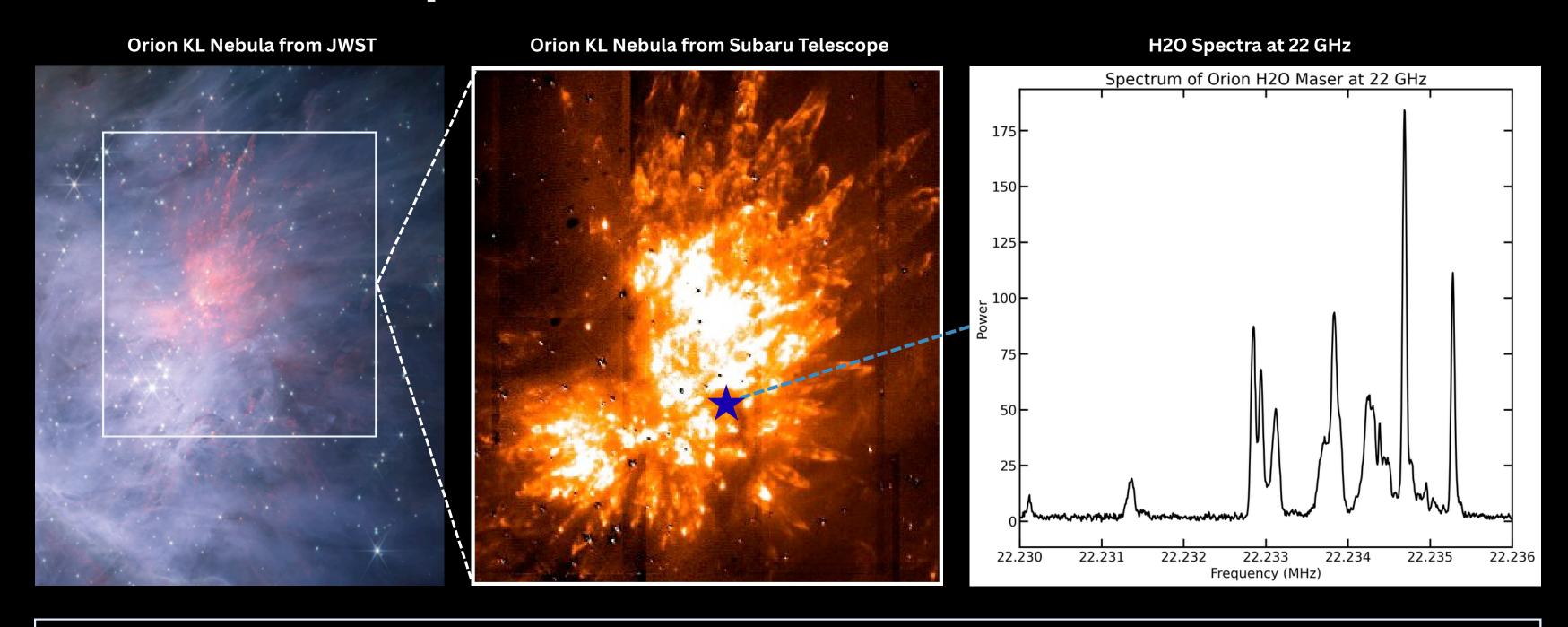
- Taurus Molecular
   Cloud 1: TMC1
- Site of current astrochemical research
- We observe ammonia spectra in TMC 1
- Proof of capability to contribute to modern astrochemical research



• From spectra, can obtain upper limit on the gas temperature and ammonia column density that agrees with the literature

$$T_{\text{kinetic}} < 10.8 \text{K}$$
  $N_{\text{NH3}} < 4.5 \times 10^{14} \text{cm}^{-2}$ 

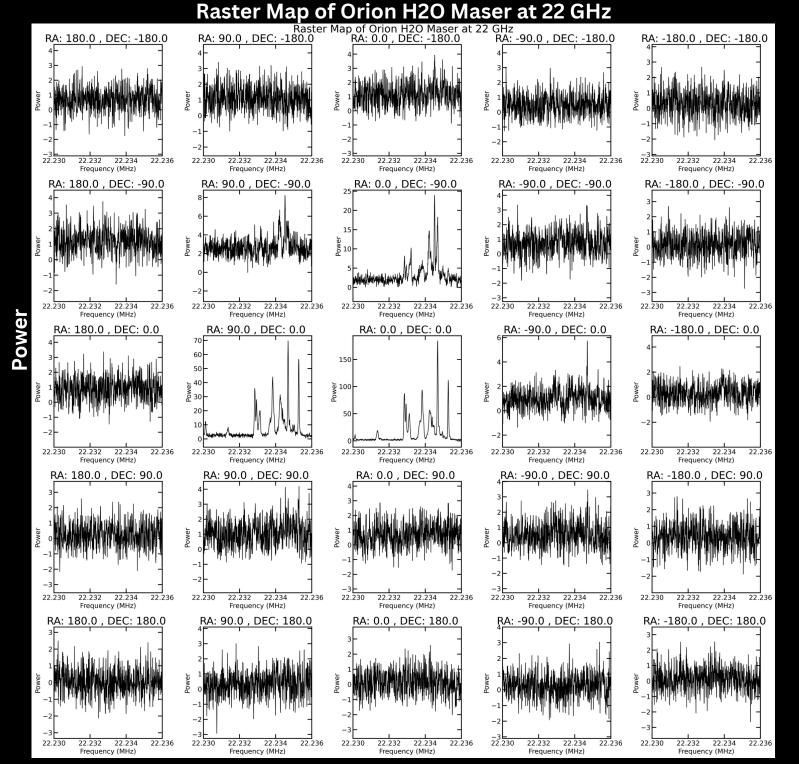
## Water Maser Spectrum in Orion-KL

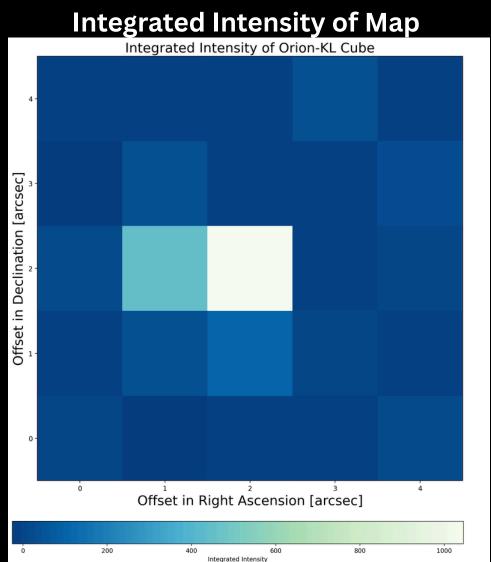


- Kleinmann-Low or Orion-KL nebula
- Active star forming region, location of past explosion event
- Contains extremely strong water maser at 22 GHz, which we observe

# Water Maser Raster Map of Orion-KL

- Create raster map around center source
- Each spectrum is spaced 90 arcsec in RA and/or Dec from the others
- Demonstrates
   functionality through
   metadata that was
   not possible prior to
   the new user
   interface.





Frequency

#### Conclusion

- Telescope closer to becoming a multi-user system
- New, user-friendly interface allows computers to easily share data within an observing session
- New Python connections allow for the collection of metadata, enabling the creation of data maps
- Variety of straightforward experiments can be conducted using the new system

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